

# ASTA

The ASTA team

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# 1 Resampling techniques

Topics:

- Overfitting (the model fits too well to the observed data)
- Generalisation (how well a model performs on a new sample)
- Cross-validation (estimate out-of-sample prediction error)
- Bootstrap (estimate standard errors)

# 2 Model complexity

---

## 2.1 A linear model for tree data

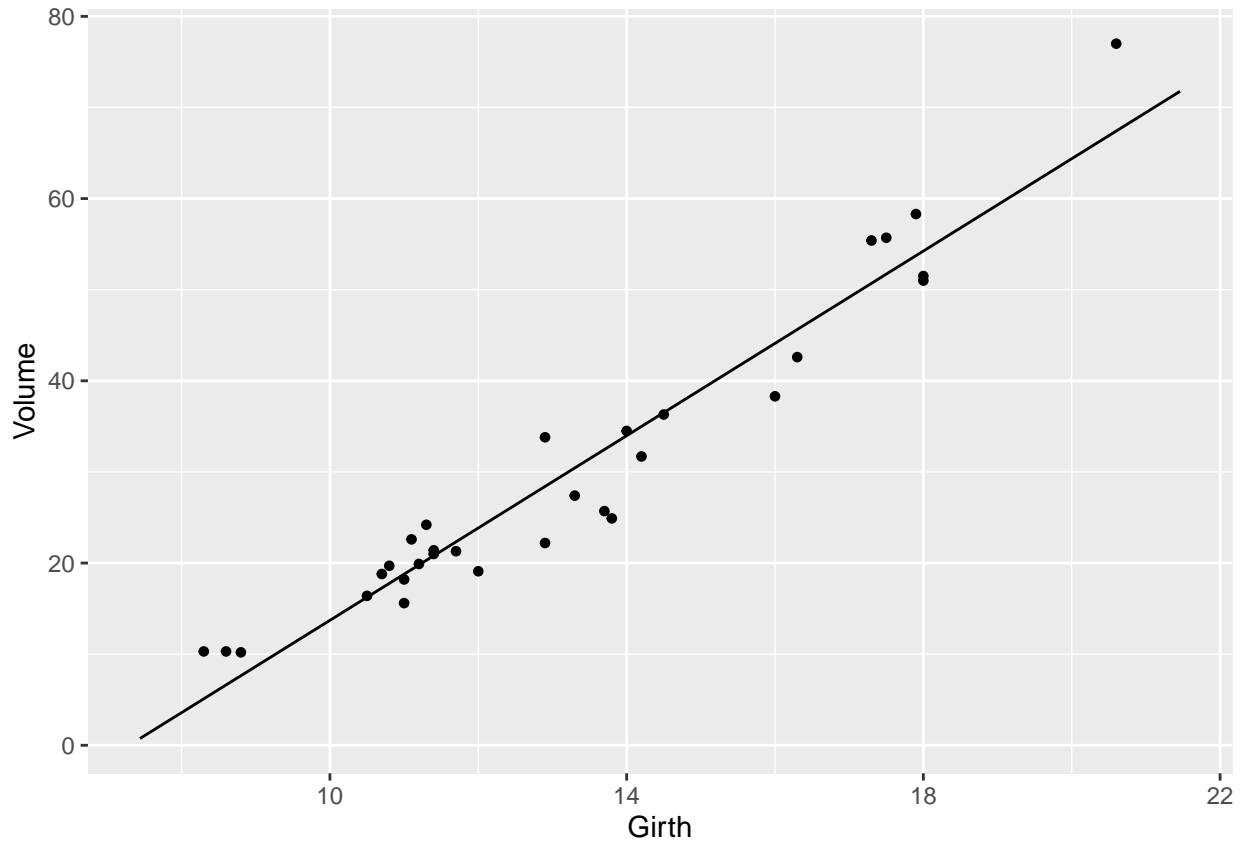
```
trees <- read.delim("https://asta.math.aau.dk/datasets?file=trees.txt")
head(trees)
```

```
##   Girth Height Volume
## 1   8.3     70     10
## 2   8.6     65     10
## 3   8.8     63     10
## 4  10.5     72     16
## 5  10.7     81     19
## 6  10.8     83     20
```

- We consider the dataset `trees` containing the following observations on 31 trees:
  - Response: Volume - timber volume
  - Predictor: Girth - the tree diameter
- We consider a linear model.

$$Y = \alpha + \beta \cdot x + \varepsilon$$

```
m0 <- lm(Volume ~ Girth, data = trees)
plotModel(m0)
```



```
summary(m0)
```

```
##
## Call:
## lm(formula = Volume ~ Girth, data = trees)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -8.065 -3.107  0.152  3.495  9.587
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  -36.943     3.365   -11.0 7.6e-12 ***
## Girth           5.066     0.247    20.5 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 4.2 on 29 degrees of freedom
## Multiple R-squared:  0.935, Adjusted R-squared:  0.933
## F-statistic: 419 on 1 and 29 DF, p-value: <2e-16
```

- We obtain the prediction equation

$$\hat{y} = -36.9 + 5.07 \cdot x$$

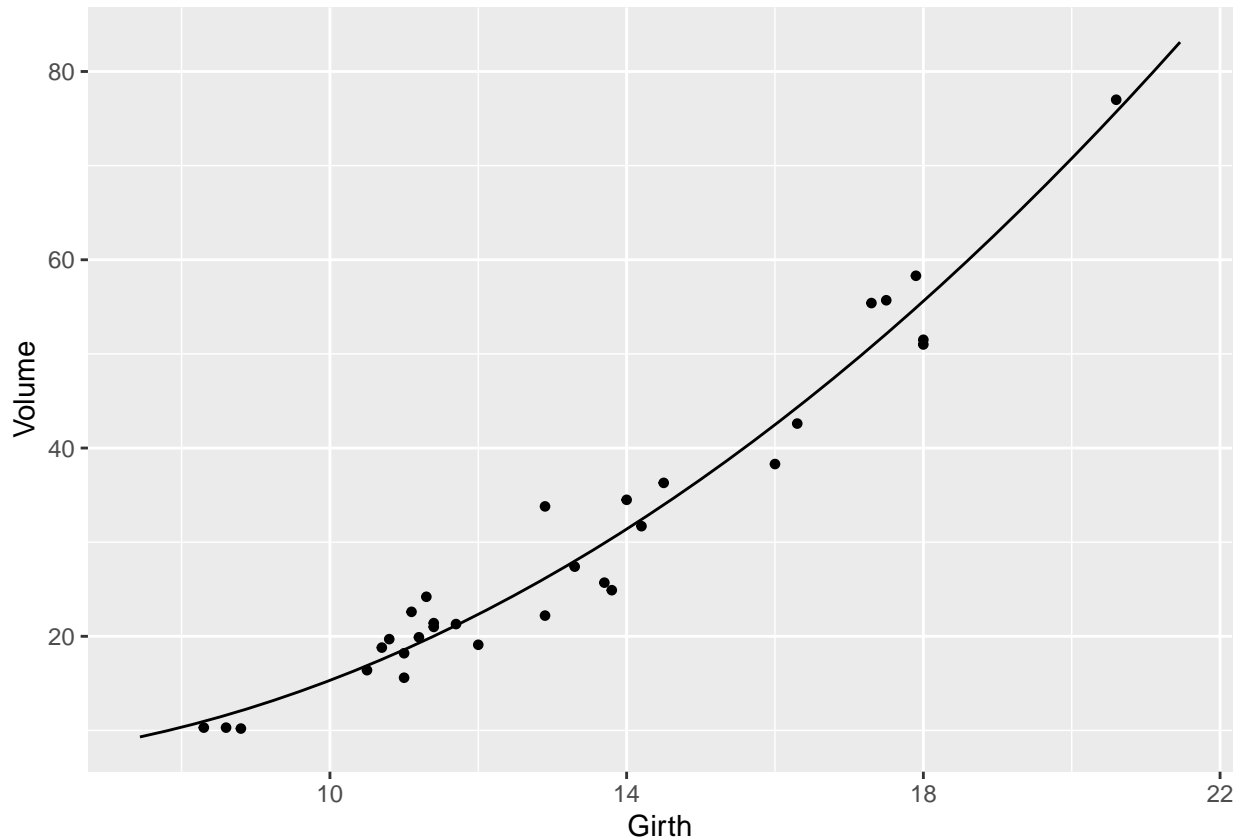
- The model has  $R^2 = 0.935$

## 2.2 A polynomial model

- We can also try to fit a second degree polynomial to the data

$$Y = \alpha + \beta_1x + \beta_2x^2 + \varepsilon$$

```
m1 <- lm(Volume ~ poly(Girth, 2), data = trees)
plotModel(m1)
```



```
summary(m1)
```

```
##
## Call:
## lm(formula = Volume ~ poly(Girth, 2), data = trees)
##
## Residuals:
##   Min     1Q   Median     3Q    Max
## -5.489 -2.429 -0.372  2.076  7.645
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)    30.171     0.599   50.37 < 2e-16 ***
## poly(Girth, 2)1  87.073     3.335   26.11 < 2e-16 ***
## poly(Girth, 2)2  14.592     3.335    4.38  0.00015 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.3 on 28 degrees of freedom
## Multiple R-squared:  0.962, Adjusted R-squared:  0.959
```

```
## F-statistic: 350 on 2 and 28 DF, p-value: <2e-16
```

- Prediction equation

$$\hat{y} = 30.2 + 87.1x + 14.6x^2$$

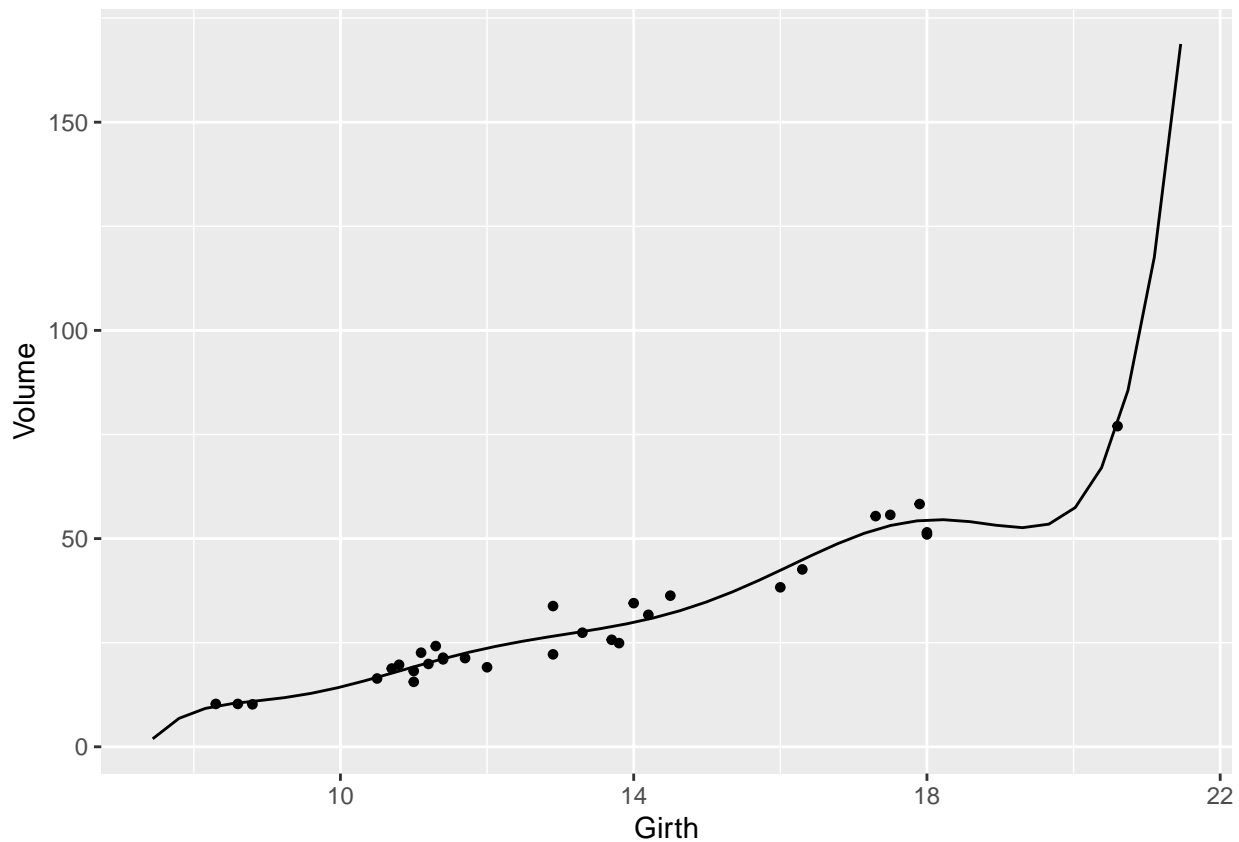
- $R^2 = 0.962$
- 

## 2.3 Another polynomial model

- Or a polynomial of degree 7

$$Y = \alpha + \beta_1x + \beta_2x^2 + \dots + \beta_7x^7 + \varepsilon$$

```
m1_bad <- lm(Volume ~ poly(Girth, 7), data = trees)
plotModel(m1_bad)
```

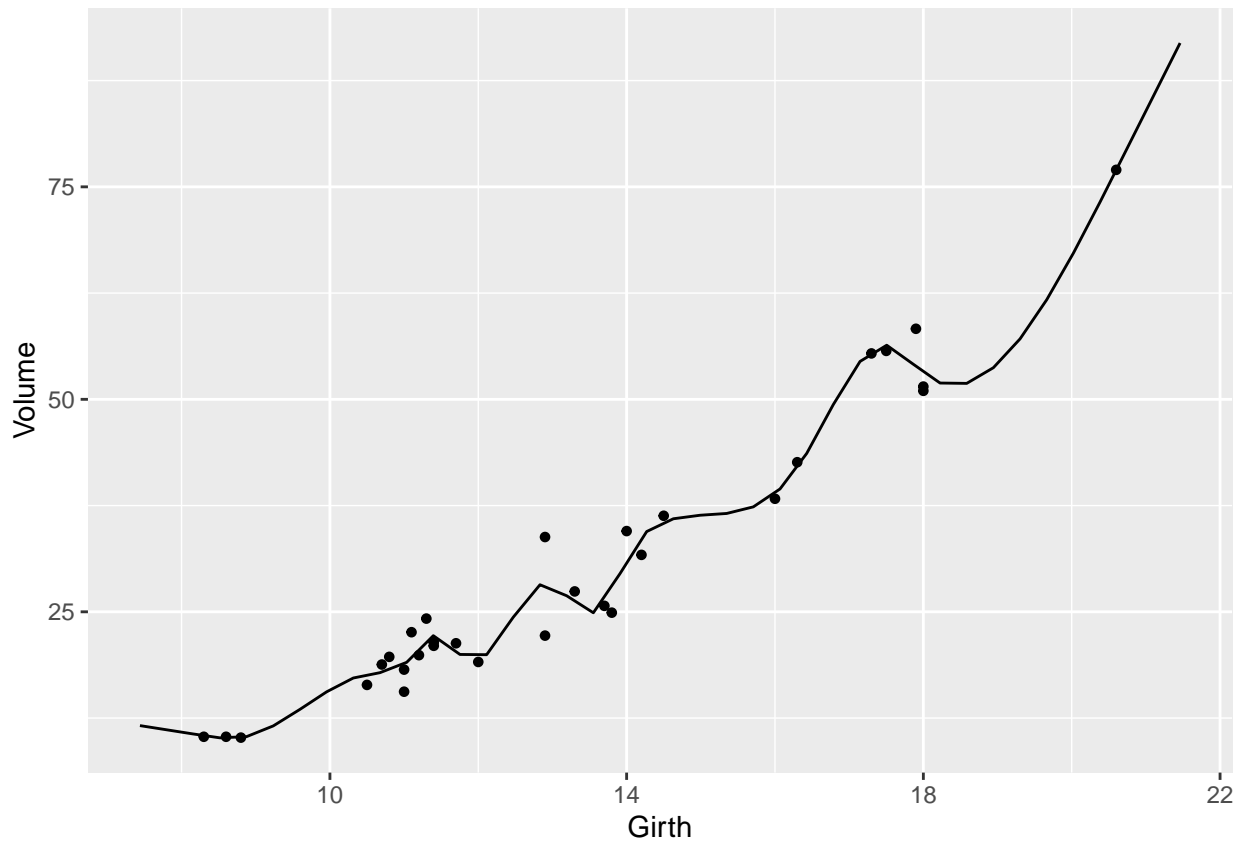


- Polynomials tend to behave wildly at the ends.
- 

## 2.4 A natural spline

- A natural spline is a piecewise third degree polynomial with smooth overlaps which is linear at the ends. It can also be fitted to the data.

```
library(splines)
m2 <- lm(Volume ~ ns(Girth, 15), data = trees)
plotModel(m2)
```



- The model is very “wiggly” to get near the data points.
- How to compare this model with the others?

### 3 Measures of fit

---

#### 3.1 $R^2$ and correlation

- We can compare the models using  $R^2$

```
summary(m0)$r.squared
```

```
## [1] 0.94
```

```
summary(m1)$r.squared
```

```
## [1] 0.96
```

```
summary(m2)$r.squared
```

```
## [1] 0.98
```

- $R^2$  is always higher for more complex models
- Note that  $R^2$  is the squared correlation between the observed response values  $y_i$  and the values predicted by the prediction equation  $\hat{y}_i$

$$R^2 = \text{cor}(y_i, \hat{y}_i)^2$$

```
# or: m0$fitted
cor(trees$Volume, predict(m0, newdata = trees))^2

## [1] 0.94

cor(trees$Volume, predict(m1, newdata = trees))^2

## [1] 0.96

cor(trees$Volume, predict(m2, newdata = trees))^2

## [1] 0.98
```

---

## 3.2 Mean squared error

- We can also compare the models using mean squared errors (MSE)

$$MSE = \frac{1}{n} \sum_i (y_i - \hat{y}_i)^2$$

```
mean((trees$Volume - predict(m0, newdata = trees))^2)

## [1] 17

mean((trees$Volume - predict(m1, newdata = trees))^2)

## [1] 10

mean((trees$Volume - predict(m2, newdata = trees))^2)

## [1] 4.9
```

- The more complicated model has lowest MSE
- The model is fitted using least squares, i.e. minimising MSE.
- The model is trained to predict the datapoints well.
  - Would it also predict well on new data points?

## 4 Out-of-sample error

---

### 4.1 Reproducibility and random number generation

- The code below generates three random numbers three times.

```
rnorm(3)

## [1] -0.35  1.53  1.04

rnorm(3)

## [1]  0.072 -1.505  0.885

rnorm(3)

## [1] -0.62 -1.12 -1.17
```

- We get a new sample in each try

- If we want to be sure we always get the same, we can set a seed.

```
set.seed(1)
rnorm(3)
```

```
## [1] -0.63  0.18 -0.84
```

```
set.seed(1)
rnorm(3)
```

```
## [1] -0.63  0.18 -0.84
```

---

## 4.2 Out-of-sample error

- Our dataset contains  $n = 31$  observations
- We now split the dataset in two:
  - A **training dataset** consisting of 20 observations
  - A **test dataset** consisting of 11 observations

```
set.seed(1)
train_idx <- sample(x = seq_len(nrow(trees)), size = 20, replace = FALSE)
trees_train <- trees[train_idx, ]
nrow(trees_train)
```

```
## [1] 20
```

```
trees_test <- trees[-train_idx, ]
nrow(trees_test)
```

```
## [1] 11
```

---

## 4.3 Training the models

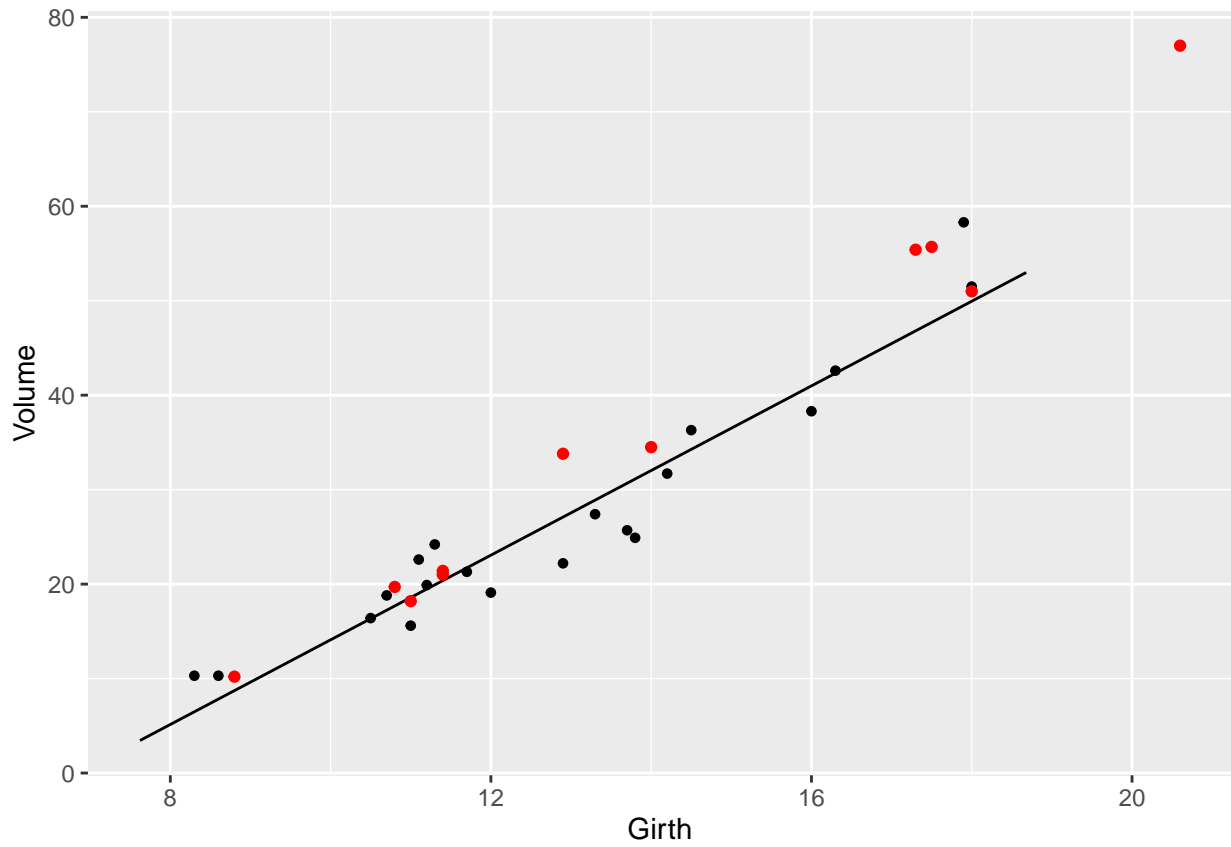
- We use only the training data for fitting the models

```
m0_train <- lm(Volume ~ Girth, data = trees_train)
m1_train <- lm(Volume ~ poly(Girth, 2), data = trees_train)
m2_train <- lm(Volume ~ ns(Girth, 15), data = trees_train)
```

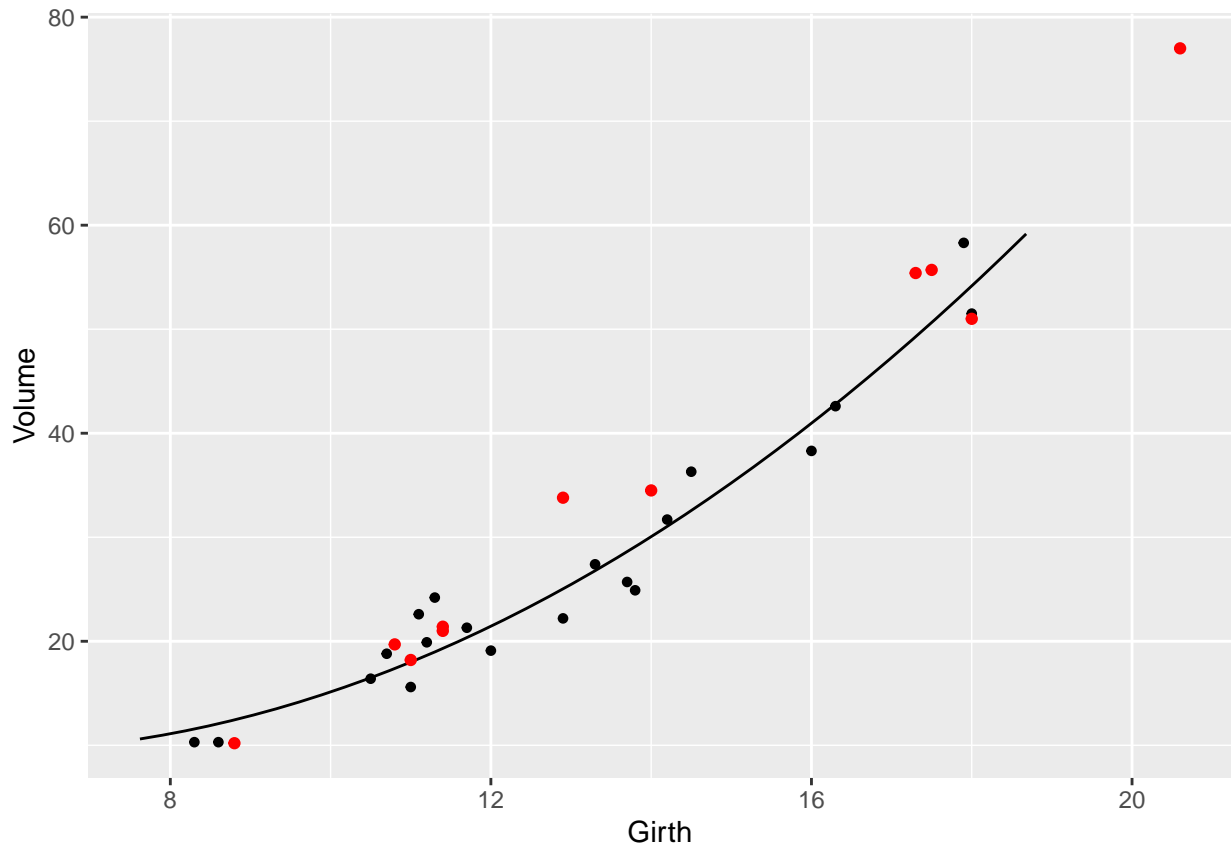
---

```
plotModel(m0_train) +
  geom_point(aes(Girth, Volume), data = trees_test, color = "red")
```

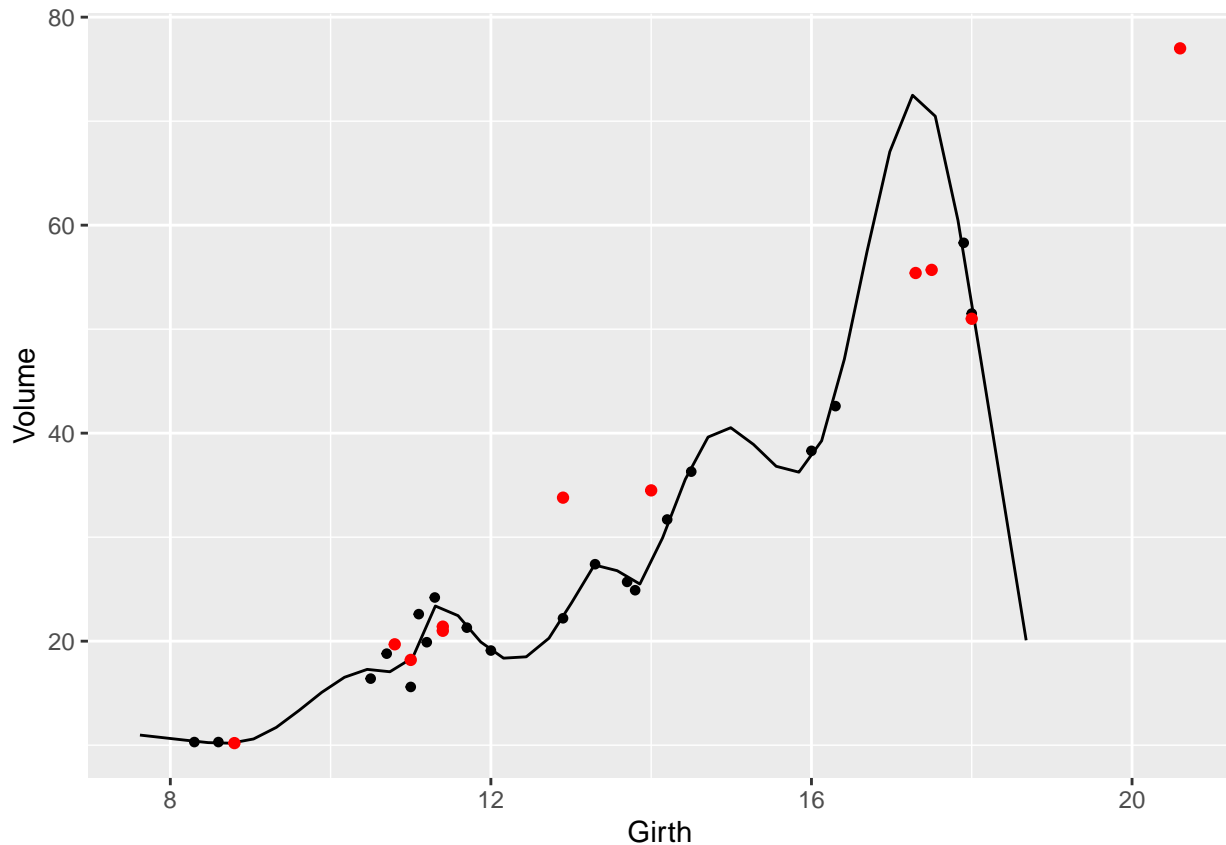




```
plotModel(m1_train) +  
  geom_point(aes(Girth, Volume), data = trees_test, color = "red")
```



```
plotModel(m2_train) +  
  geom_point(aes(Girth, Volume), data = trees_test, color = "red")
```



#### 4.4 Testing the models

- We now use the test dataset to test the models
  - We predict the response in the test dataset
  - We then compare the predictions to the observed response

```
cor(predict(m0_train, newdata = trees_test), trees_test$Volume)^2
```

```
## [1] 0.98
```

```
cor(predict(m1_train, newdata = trees_test), trees_test$Volume)^2
```

```
## [1] 0.97
```

```
cor(predict(m2_train, newdata = trees_test), trees_test$Volume)^2
```

```
## [1] 0.016
```

- The linear model has the highest correlation between observations and predictions

```
mean((predict(m0_train, newdata = trees_test) - trees_test$Volume)^2)
```

```
## [1] 40
```

```
mean((predict(m1_train, newdata = trees_test) - trees_test$Volume)^2)
```

```
## [1] 17
```

```
mean((predict(m2_train, newdata = trees_test) - trees_test$Volume)^2)
```

## [1] 2074

- The quadratic polynomial has the smallest MSE
- 

## 4.5 Summary

- When we test on the same data as we train the model on, we get lower MSE and higher  $cor(y_i, \hat{y}_i)$  for the more complex model
- When we test on new data, the more complicated model does not predict well
- **Overfitting:** A complex model tends to fit too well to the training data, but does not fit well to new data.

## 5 Cross-validation

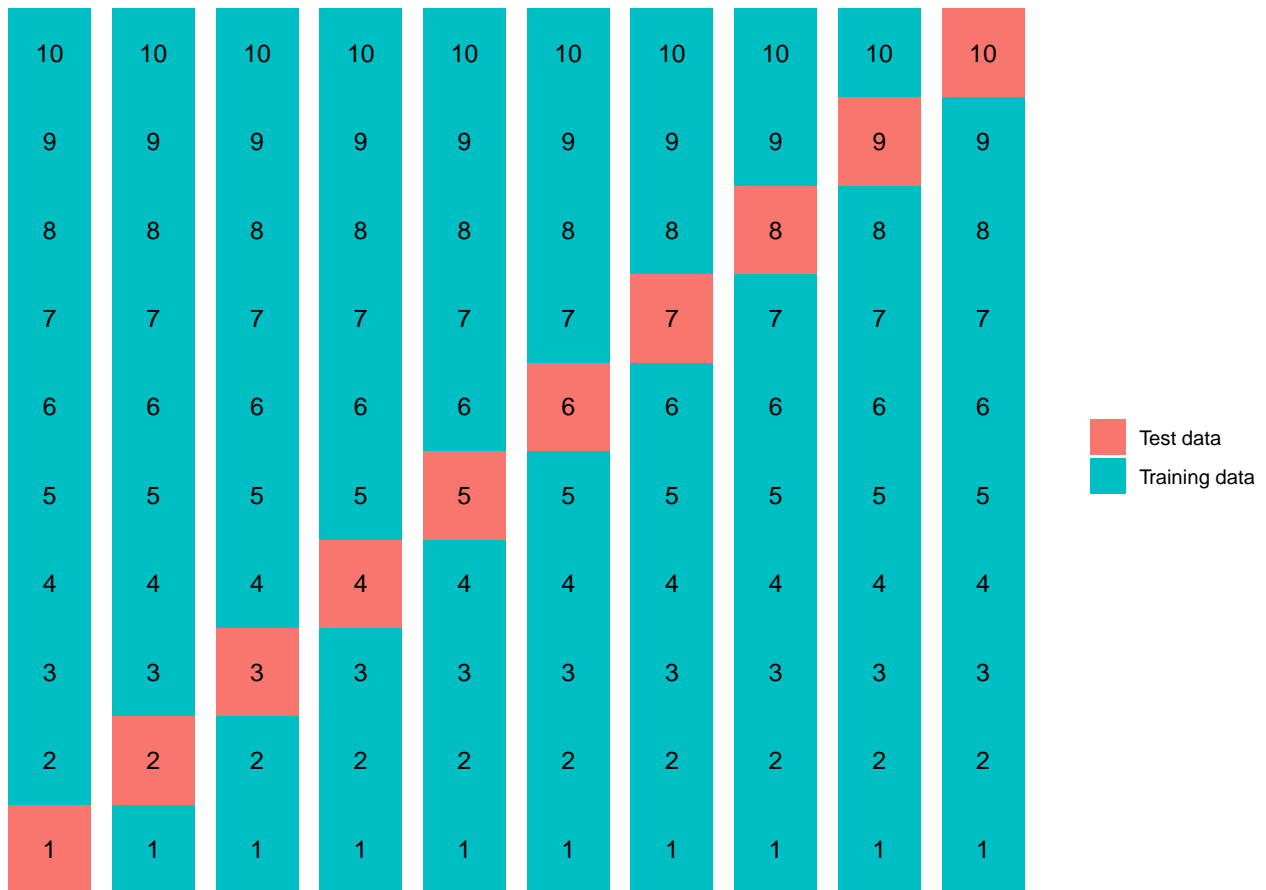
---

### 5.1 Testing predictive ability

- Ideally, we should test a models predictive ability on new data that was not used to fit the model
  - Typically, only one dataset is available
    - A solution could be to split the dataset in test and training data
    - Waste of data
  - Solution: repeat the splitting of data multiple times
- 

### 5.2 Cross-validation

- Cross-validation provides a clever way of repeating the training and test of a model
- Divide data into  $k$  folds
- In each iteration, fit the model on  $k - 1$  folds, test on the last fold
- E.g.  $k$ -fold cross validation for  $k = 10$ :



- Benefits:
  - We use most of the data for fitting the model
  - Each observation is used once for testing

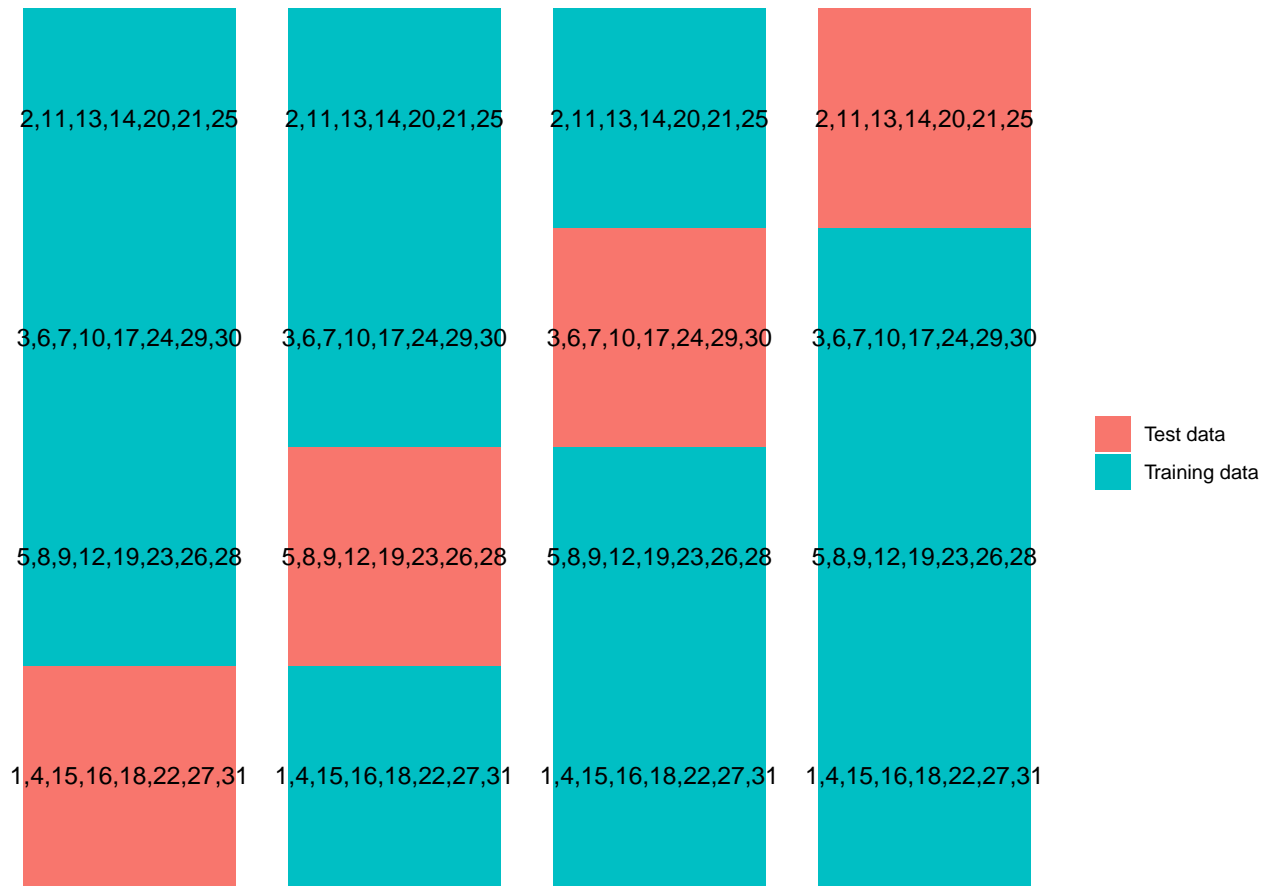
---

### 5.3 Example

- Number of folds depends on size of dataset (often  $k = 5$  or  $k = 10$ )
- We have 31 observations
- 4-fold cross validation seems suitable
- Divide data into 4 fold

2,11,13,14,20,21,25
3,6,7,10,17,24,29,30
5,8,9,12,19,23,26,28
1,4,15,16,18,22,27,31

- “Rotate” which folds are training data and which one is test data:



## 5.4 Repeated CV

- Cross-validation may be repeated several times

2,11,13,14,20,21,25	7,9,11,15,21,27,28	1,3,5,6,9,12,24	3,11,12,14,19,23,24	4,8,14,15,17,20,27
3,6,7,10,17,24,29,30	1,6,10,12,14,16,22,24,27,10,13,17,22,23,28,30		1,2,4,8,9,16,29,30	2,3,10,12,13,23,25,28
5,8,9,12,19,23,26,28	2,3,5,13,18,19,25,29,8,11,18,19,21,25,26,27,5,6,10,13,17,21,27,28			1,7,9,16,18,22,24,30
1,4,15,16,18,22,27,31	4,8,17,20,23,26,30,31	2,4,14,15,16,20,29,31	7,15,18,20,22,25,26,31	5,6,11,19,21,26,29,31

---

## 5.5 Cross-validation in R

- The caret package can be used for cross-validation in R

```
library(caret)
```

<https://cran.r-project.org/package=caret>

<https://topepo.github.io/caret/>

- We first set up the cross-validation

```
train_control <- trainControl(method = "repeatedcv",
                              # k-fold CV
                              number = 4,
                              # repeated five times
                              repeats = 5)
```

- Then we carry out the cross-validation

```
set.seed(1)
m0_cv <- train(Volume ~ Girth, data = trees, trControl = train_control, method = "lm")
m1_cv <- train(Volume ~ poly(Girth, 2), data = trees, trControl = train_control, method = "lm")
m2_cv <- train(Volume ~ ns(Girth, 15), data = trees, trControl = train_control, method = "lm")
```



## 5.6 Result of cross-validation

```
m0_cv
```

```
## Linear Regression
##
## 31 samples
## 1 predictor
##
## No pre-processing
## Resampling: Cross-Validated (4 fold, repeated 5 times)
## Summary of sample sizes: 24, 23, 23, 23, 23, 23, ...
## Resampling results:
##
##   RMSE  Rsquared  MAE
##   4.5   0.95     3.7
##
## Tuning parameter 'intercept' was held constant at a value of TRUE
```

- **RMSE** is root mean squared error
- 

## 5.7 More on RMSE

- Here is the resulting RMSE for all folds and all repetitions:

```
m0_cv$resample
```

```
##   RMSE Rsquared MAE  Resample
## 1   4.7   0.91 4.2 Fold1.Rep1
## 2   4.2   0.91 3.6 Fold2.Rep1
## 3   5.3   0.99 3.3 Fold3.Rep1
## 4   4.7   0.96 4.2 Fold4.Rep1
## 5   3.8   0.93 3.2 Fold1.Rep2
## 6   5.6   0.93 4.6 Fold2.Rep2
## 7   2.7   0.97 2.0 Fold3.Rep2
## 8   5.0   0.95 4.7 Fold4.Rep2
## 9   3.5   0.97 2.7 Fold1.Rep3
## 10  4.7   0.93 4.2 Fold2.Rep3
## 11  4.6   0.96 3.6 Fold3.Rep3
## 12  5.2   0.96 4.2 Fold4.Rep3
## 13  4.4   0.93 3.6 Fold1.Rep4
## 14  5.3   0.95 4.2 Fold2.Rep4
## 15  3.5   0.96 2.7 Fold3.Rep4
## 16  4.1   0.95 3.4 Fold4.Rep4
## 17  3.7   0.98 3.0 Fold1.Rep5
## 18  4.4   0.92 3.7 Fold2.Rep5
## 19  6.2   0.98 4.6 Fold3.Rep5
## 20  4.8   0.92 4.2 Fold4.Rep5
```

- The average of these RMSE is the total RMSE

```
mean(m0_cv$resample$RMSE)
```

```
## [1] 4.5
```

- This can also be obtained directly via the code

```
m0_cv$results$RMSE
```

```
## [1] 4.5
```

---

## 5.8 Model comparison

- We obtain the model **RMSE** for the three models

```
m0_cv$results$RMSE
```

```
## [1] 4.5
```

```
m1_cv$results$RMSE
```

```
## [1] 3.5
```

```
m2_cv$results$RMSE
```

```
## [1] 86
```

- The quadratic model has the lowest **RMSE** and hence the best predictive power

## 6 Non-parametric bootstrap

---

### 6.1 Sampling variability

- When we estimate a parameter from a sample, there is some uncertainty due to the fact that the sample is random
  - A new sample would result in new estimates
  - The standard error is the standard deviation of the estimate when we repeat the sampling many times
    - Measures the uncertainty of the estimate
  - However, we only have one sample available
- 

### 6.2 Bootstrap principle

- Idea: Create new samples by resampling  $n$  observations from original data with replacement (the same observation may be sampled several times)
- Mimic new samples
- **Example:** Data indices:

```
index<-c(1,2,3,4,5)
```

- Bootstrap sample indices:

```
set.seed(1)
boot_index<-sample(index, replace = TRUE)
boot_index
```

```
## [1] 1 4 1 2 5
```

- Observation 1 appears 2 times in Bootstrap sample

---

### 6.3 Bootstrap data example

- We want to fit a linear model on the tree data. Coefficients of the linear model can be extracted by

```
m0 <- lm(Volume ~ Girth, data = trees)
coef(m0)
```

```
## (Intercept)      Girth
##          -36.9      5.1
```

- We want to estimate their standard errors using bootstrap.
- To prepare for the bootstrap, we define a function that takes as input a vector of indices of the bootstrap observations and does linear regression and extracts coefficients:

```
model_coef <- function(index){
  coef(lm(Volume ~ Girth, data = trees, subset = index))
}
model_coef(1:nrow(trees))
```

```
## (Intercept)      Girth
##          -36.9      5.1
```

```
set.seed(1)
model_coef(sample(1:nrow(trees), replace = TRUE))
```

```
## (Intercept)      Girth
##          -29.8      4.5
```

```
model_coef(sample(1:nrow(trees), replace = TRUE))
```

```
## (Intercept)      Girth
##          -34.4      4.8
```

---

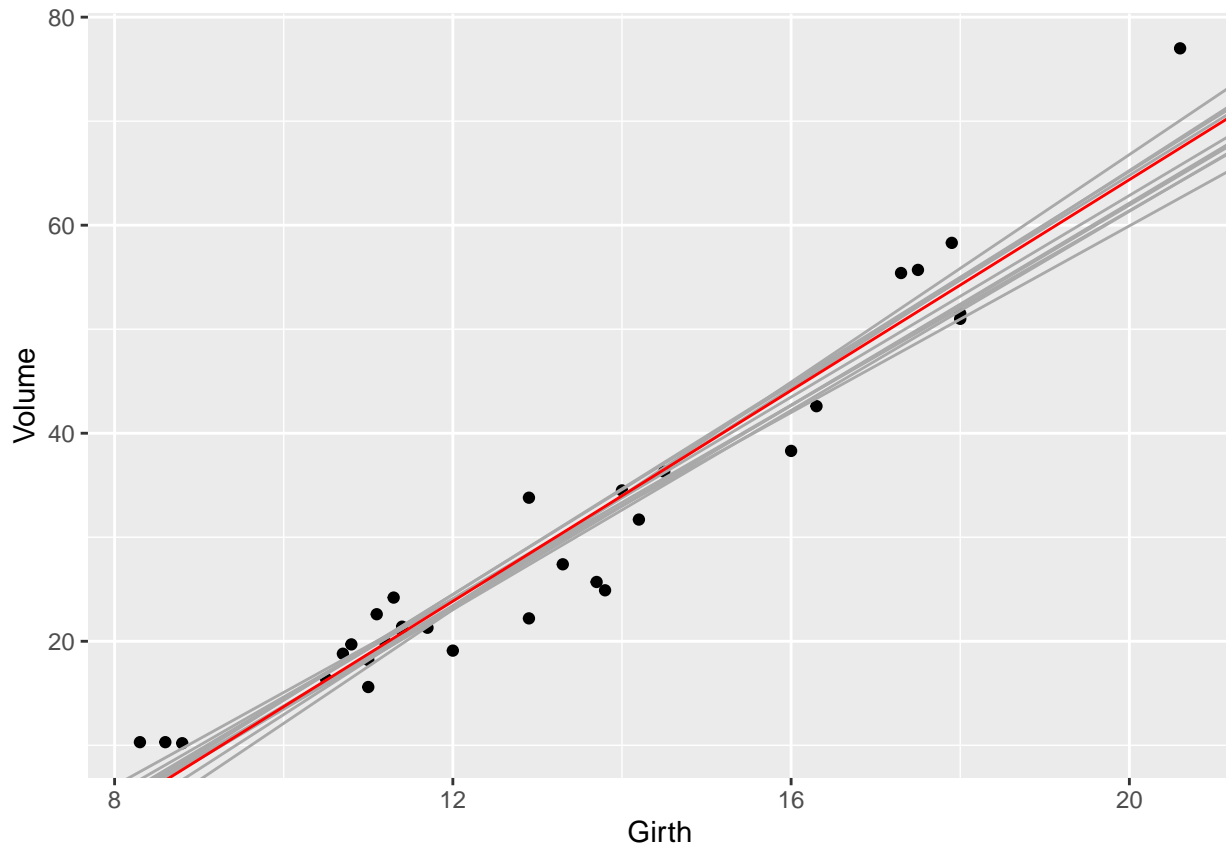
### 6.4 Bootstrap data example - continued

- We now create 1000 bootstrap samples and estimate the linear regression coefficients for each
- We view the first ten results

```
set.seed(1)
bootstrap_coefs <- replicate(1000, {
  model_coef(sample(1:nrow(trees), replace = TRUE))
})
bootstrap_coefs[, 1:10]
```

```
##           [,1] [,2] [,3] [,4] [,5] [,6] [,7] [,8] [,9] [,10]
## (Intercept) -29.8 -34.4 -34.3 -42.6 -36 -35.0 -36.5 -39.4 -34.0 -32.1
## Girth       4.5  4.8  4.8  5.5  5  4.9  5.1  5.2  4.8  4.7
```

- Below we plot the regression lines for the original data (red) and for the first ten bootstrap samples (black)



## 6.5 Bootstrap estimates for the standard error

- We estimate the standard error by taking the standard deviation of the 1000 parameter estimates

```
apply(bootstrap_coefs, 1, sd) # applies the function sd to each row in the matrix bootstrap_coefs
```

```
## (Intercept)      Girth
##          3.98      0.32
```

- This can be compared to the standard errors found by `lm()` using theoretical formulas

```
summary(m0)
```

```
##
## Call:
## lm(formula = Volume ~ Girth, data = trees)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -8.065  -3.107   0.152   3.495   9.587
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  -36.943     3.365  -11.0 7.6e-12 ***
## Girth         5.066     0.247   20.5 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
##
## Residual standard error: 4.2 on 29 degrees of freedom
## Multiple R-squared:  0.935, Adjusted R-squared:  0.933
## F-statistic: 419 on 1 and 29 DF, p-value: <2e-16
```

---

## 6.6 The boot package

- Bootstrapping can be done automatically using the `boot` package in R: <https://cran.r-project.org/package=boot>

```
library(boot)
```

- We now need a function of both the dataset and an index vector that returns the linear regression coefficients.

```
model_coef_boot <- function(data, index){
  coef(lm(Volume ~ Girth, data = data, subset = index))
}
```

- Then the bootstrap is carried out as follows

```
set.seed(1)
b <- boot(trees, model_coef_boot, R = 1000)
b
```

```
##
## ORDINARY NONPARAMETRIC BOOTSTRAP
##
##
## Call:
## boot(data = trees, statistic = model_coef_boot, R = 1000)
##
##
## Bootstrap Statistics :
##   original  bias  std. error
## t1*    -36.9  0.372     4.05
## t2*     5.1 -0.038     0.33
```

```
coef(summary(m0))
```

```
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept)   -36.9      3.37    -11 7.6e-12
## Girth           5.1      0.25     20 8.6e-19
```

## 7 Bootstrap by resampling residuals

- Idea:
  - First fit regression line
  - Compute residuals  $\hat{\epsilon}_i = y_i - \hat{y}_i$
  - Create new dataset by replacing  $y_i$  by  $\hat{y}_i + \hat{\epsilon}_{i,new}$ , where  $\hat{\epsilon}_{i,new}$  is randomly sampled from the residuals  $\hat{\epsilon}_j$
- Can be used if residuals are not normally distributed
- First fit the model

```
m0 <- lm(Volume ~ Girth, data = trees)
```

- Construct 1000 new samples with resampled residuals.

```
set.seed(1)
res_bootstrap_coefs <- replicate(1000, {
  new_y <- m0$fitted.values + sample(m0$residuals, replace = TRUE)
  coef(lm(new_y ~ trees$Girth))
})
```

- Compute the regression parameters for each sample and find standard deviation

```
res_bootstrap_coefs[, 1:10]
```

```
##           [,1] [,2] [,3] [,4] [,5] [,6] [,7] [,8] [,9] [,10]
## (Intercept) -38.4 -38.5 -34.0 -36  -35 -31.7 -38.6 -40.8 -30.5 -38.8
## trees$Girth  5.2  5.1  4.8   5   5   4.6  5.2  5.3  4.6  5.2
```

```
apply(res_bootstrap_coefs, 1, sd)
```

```
## (Intercept) trees$Girth
##           3.31         0.24
```

- Compare with ordinary bootstrap

```
apply(bootstrap_coefs, 1, sd)
```

```
## (Intercept)      Girth
##           3.98         0.32
```

- Compare with `lm()`

```
coef(summary(m0))
```

```
##           Estimate Std. Error t value Pr(>|t|)
## (Intercept)   -36.9         3.37   -11 7.6e-12
## Girth          5.1          0.25    20 8.6e-19
```

## 8 Maximum likelihood estimation of a probability

---

### 8.1 Estimating a probability

- Assume that we want to estimate a probability  $p$  of a certain event, e.g.
  - the probability that a bank customer will default their loan
  - the probability that a customer will buy a certain product
- We take a sample of  $n$  observations  $Y_1, \dots, Y_n$ , where
  - $Y_i = 1$  if the event happens,
  - $Y_i = 0$  if the event does not happen,
  - The  $Y_i, i = 1, \dots, n$ , are independent random variables with  $P(Y_i = 1) = p$ .
- Let  $X = \sum_i Y_i$  be the number of ones in our sample. The natural estimate for  $p$  is

$$\hat{p} = \frac{X}{n}.$$

- Theoretical justification?
-

## 8.2 The likelihood function

- Idea: choose  $\hat{P}$  to be the value of  $p$  that makes our observations *as likely as possible*.
- Suppose we have observed  $Y_1 = y_1, \dots, Y_n = y_n$ . The probability of observing this is

$$P(Y_1 = y_1, \dots, Y_n = y_n) = P(Y_1 = y_1) \cdots P(Y_n = y_n).$$

- Note that

$$P(Y_i = y_i) = \begin{cases} p, & y_i = 1, \\ (1 - p), & y_i = 0. \end{cases}$$

- Therefore, if we let  $x = \sum_i y_i$  be the number of 1's in our sample,

$$P(Y_1 = y_1, \dots, Y_n = y_n) = p^x \cdot (1 - p)^{(n-x)}.$$

- This probability depends on the value of  $p$ . We may think of it as a function

$$L(p) = P(Y_1 = y_1, \dots, Y_n = y_n) = p^x \cdot (1 - p)^{(n-x)}.$$

– This is called the **likelihood function**.

- The **maximum likelihood estimate**  $\hat{p}$  is the value of  $p$  that maximizes the likelihood function.

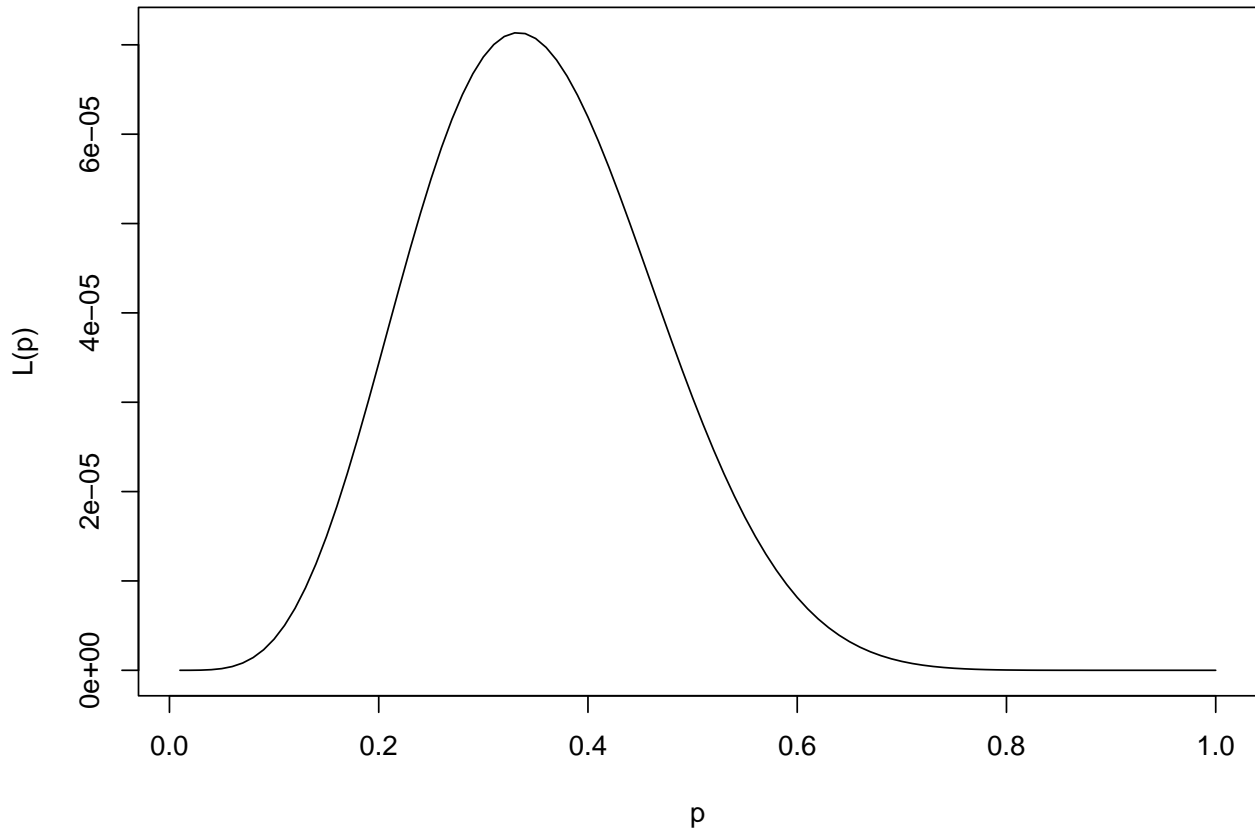
---

## 8.3 Likelihood function - example

- **Example:** Suppose we take a sample of  $n = 15$  observations. We observe 5 ones and 10 zeros. The likelihood function becomes

$$L(p) = p^5(1 - p)^{10}$$

- We plot the graph of  $L(p)$ :



- The probability of our observations seems to be largest when  $p$  is around  $1/3$ .
- 

#### 8.4 The log-likelihood function

- We seek the value of  $p$  that maximizes the likelihood function

$$L(p) = p^x \cdot (1 - p)^{(n-x)}.$$

- Recall that  $\ln(x)$  is a strictly increasing function.
- The value of  $p$  that maximizes  $L(p)$  also maximizes  $\ln(L(p))$ .
- This is the **log-likelihood function**

$$l(p) = \ln(L(p)) = x \ln(p) + (n - x) \ln(1 - p).$$

- It is often easier to maximize the log-likelihood function.
- 

#### 8.5 Maximum likelihood estimation

- In order to maximize

$$l(p) = x \ln(p) + (n - x) \ln(1 - p),$$

we differentiate

$$l'(p) = \frac{x}{p} - \frac{n - x}{1 - p}.$$



- The maximum must be found in a point with  $l'(p) = 0$ . Thus, we solve

$$l'(p) = \frac{x}{p} - \frac{n-x}{1-p} = 0.$$

- Multiply by  $p(1-p)$  to get

$$\begin{aligned} x(1-p) - (n-x)p &= 0 \\ x - xp - np + xp &= 0 \\ x &= np \\ p &= \frac{x}{n}. \end{aligned}$$

- Note that this must indeed be a maximum point since

$$\lim_{p \rightarrow 0} l(p) = \lim_{p \rightarrow 1} l(p) = -\infty.$$

- Our **maximum likelihood estimate** of  $p$  is  $\hat{p} = \frac{x}{n}$ .

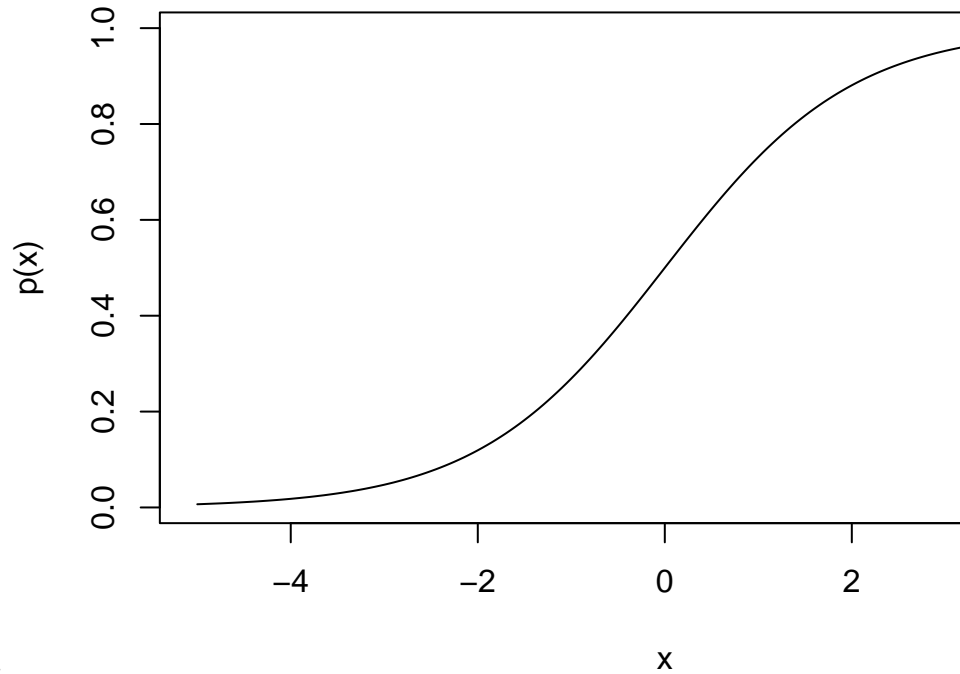
## 9 Maximum likelihood for logistic regression

---

### 9.1 The logistic regression model

- Estimation of a probability was a simple use of maximum likelihood estimation, which could easily have been treated by more direct methods.
- **Logistic regression** is a more complex case, where we want to model a probability  $p(x)$  that depends on a predictor variable  $x$ .
  - E.g. the probability of a customer buying a certain product as a function of their monthly income.
- In logistic regression,  $p(x)$  is modelled by a logistic function

$$p(x) = \frac{1}{1 + e^{-(\alpha + \beta x)}}.$$



- Graph of  $p(x)$  when  $\alpha = 0$  and  $\beta = 1$ .
  - $\alpha$  determines how steep the graph is.
  - $\beta$  shifts the graph along the  $x$ -axis.
- How to estimate  $\alpha$  and  $\beta$ ?

## 9.2 Maximum likelihood estimation for logistic regression

- A sample consists of  $(x_1, y_1), \dots, (x_n, y_n)$ , where  $x_i$  is the predictor and  $y_i$  is the response, which is either 0 or 1.
- The probability of our observations is

$$P(Y_1 = y_1, \dots, Y_n = y_n) = \prod_i p(Y_i = y_i) = \prod_i p(x_i)^{y_i} (1 - p(x_i))^{1 - y_i}$$

since

$$p(x_i)^{y_i} (1 - p(x_i))^{1 - y_i} = \begin{cases} p(x_i), & y_i = 1, \\ 1 - p(x_i), & y_i = 0. \end{cases}$$

- Inserting what  $p(x_i)$  is, we obtain a function of the unknown parameters  $\alpha$  and  $\beta$ :

$$L(\alpha, \beta) = P(Y_1 = y_1, \dots, Y_n = y_n) = \prod_i \left( \frac{1}{1 + e^{-(\alpha + \beta x_i)}} \right)^{y_i} \left( 1 - \frac{1}{1 + e^{-(\alpha + \beta x_i)}} \right)^{1 - y_i}$$

- Again, it is easier to maximize the log-likelihood

$$l(\alpha, \beta) = \sum_i \left( y_i \ln(p(x_i)) + (1 - y_i) \ln(1 - p(x_i)) \right).$$

- However, this maximum can only be found using numerical methods.

### 9.3 Logistic regression - example

- We consider a dataset from the ISLR package on whether or not 10000 bank costumers will default their loans.
  - Response: default (1=yes, 0=no)
  - Predictor: income

```
library(ISLR)
x<-Default$income/10000 # Annual income in 10000 dollars
y<-as.numeric(Default$default=="Yes") # Loan default, 1 means "Yes"
```

- We want to model the probability of default as a logistic function of income

$$p(x) = \frac{1}{1 + e^{-(\alpha + \beta x)}}.$$

---

### 9.4 Logistic regression - example continued

- We make a function in R that computes the log-likelihood function as a function of the vector  $\theta = (\alpha, \beta)^T$ .
  - We first compute a vector px that contains all the probabilities  $p(x_i)$ .
  - Then we compute the vector logpy which contains all the  $\ln(P(Y_i = y_i)) = y_i \ln(p(x_i)) + (1 - y_i) \ln(1 - p(x_i))$ .
  - Finally, we compute the log-likelihood with the formula

$$l(\alpha, \beta) = \sum_i \left( y_i \ln(p(x_i)) + (1 - y_i) \ln(1 - p(x_i)) \right)$$

```
loglik <- function(theta) {
  alpha=theta[1]
  beta=theta[2]
  px<-1/(1+exp(-alpha-beta*x))
  logpy<-y*log(px) + (1-y)*log(1-px)
  sum(logpy)
}
```

```
loglik(c(2,2))
```

```
## [1] -84250
```

- We maximize the log-likelihood using the `optim()` function in R.
  - It needs an initial guess of  $\theta$ . Here we use `c(2,2)`.
  - The option `control=list(fnscale=-1)` ensures that we maximize rather than minimize.

```
optim(c(2,2),loglik,control=list(fnscale=-1))
```

```
## $par
## [1] -3.099 -0.081
##
## $value
## [1] -1458
##
## $counts
## function gradient
##      69      NA
##
## $convergence
## [1] 0
##
```

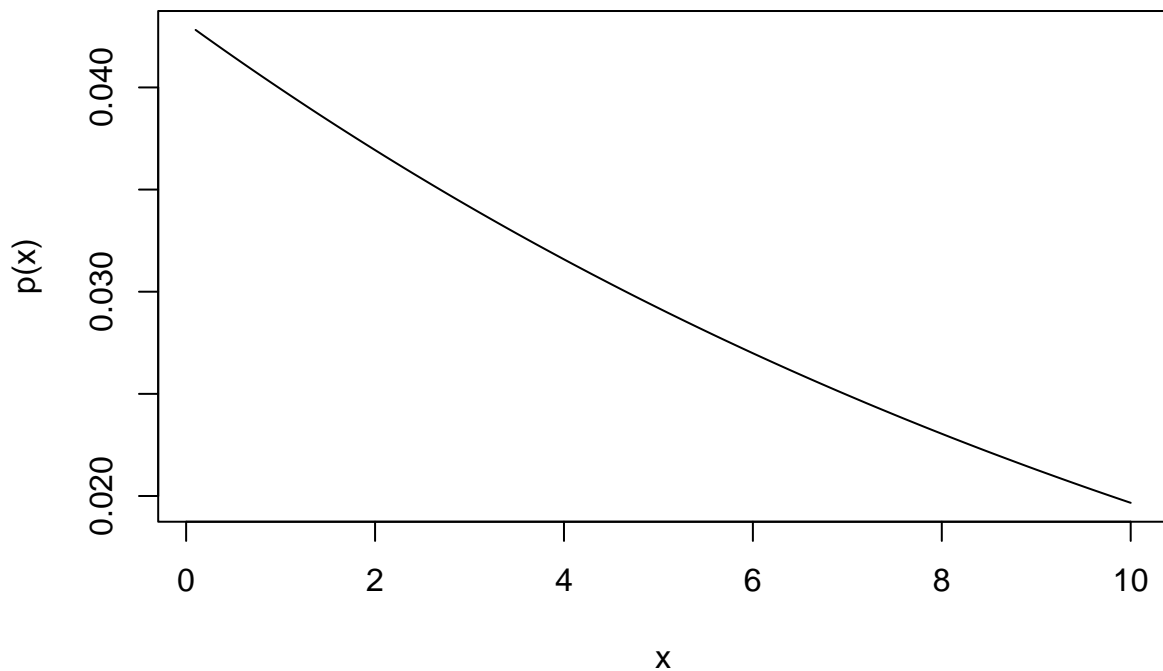
```
## $message
## NULL
```

- We obtain the maximum likelihood estimates  $\hat{\alpha} = -3.099$  and  $\hat{\beta} = -0.081$ .
- 

## 9.5 Logistic regression - example continued

- We can plot the estimated logistic function

$$\hat{p}(x) = \frac{1}{1 + e^{3.099 + 0.081x}}$$



- The maximum likelihood estimates of  $\alpha$  and  $\beta$  can be found directly using R:

```
model<-glm(y~x,family="binomial")
summary(model)

##
## Call:
## glm(formula = y ~ x, family = "binomial")
##
## Coefficients:
##             Estimate Std. Error z value Pr(>|z|)
## (Intercept) -3.0941     0.1463  -21.16  <2e-16 ***
## x           -0.0835     0.0421   -1.99   0.047 *
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for binomial family taken to be 1)
##
## Null deviance: 2920.6  on 9999  degrees of freedom
## Residual deviance: 2916.7  on 9998  degrees of freedom
## AIC: 2921
```

```
##  
## Number of Fisher Scoring iterations: 6
```

## 10 Maximum likelihood estimation with continuous variables

---

### 10.1 The probability density function

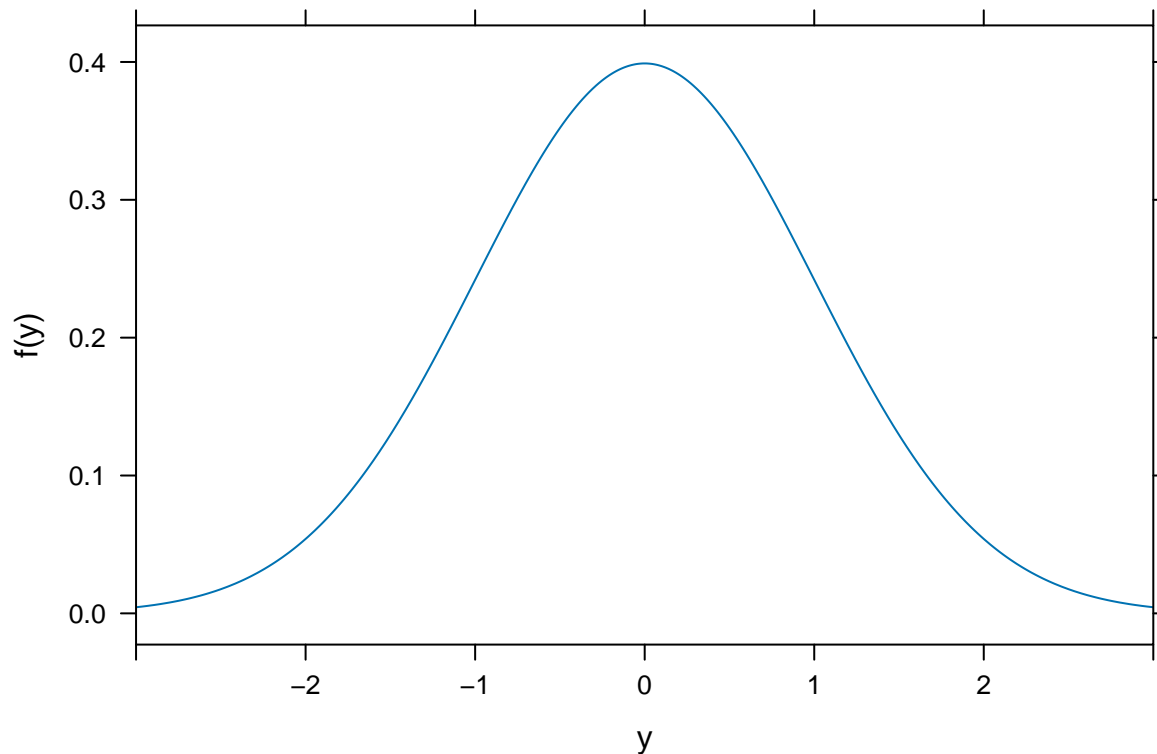
- Suppose we have a sample  $Y_1, \dots, Y_n$  of independent variables with

$$Y_i \sim N(\mu, \sigma)$$

- We would like to estimate the unknown parameters  $\mu$  and  $\sigma$ .
- For a continuous variable  $Y$  we have  $P(Y = y) = 0$  for all  $y$ .
  - We cannot use the probability of observing a given outcome to define the likelihood function.
- Instead we consider the probability density function

$$f(y) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{1}{2}\left(\frac{y-\mu}{\sigma}\right)^2\right]$$

- E.g. for  $\mu = 0$  and  $\sigma = 1$ :



- The most likely values are the ones where  $f(y)$  is large.
  - Thus we will use  $f(y)$  as a measure of how likely it is to observe  $Y = y$ .
-

## 10.2 The likelihood function for $n$ observations

- Since  $Y_1, \dots, Y_n$  are independent observations, the joint density function becomes a product of marginal densities:

$$f_{(Y_1, \dots, Y_n)}(y_1, \dots, y_n) = \prod_i f_{Y_i}(y_i).$$

- If we have observed a sample  $Y_1 = y_1, \dots, Y_n = y_n$ , our likelihood function is defined as

$$L(\mu, \sigma) = f_{(Y_1, \dots, Y_n)}(y_1, \dots, y_n) = \prod_i f_{Y_i}(y_i) = \prod_i \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y_i - \mu)^2}{2\sigma^2}}. \quad (1)$$

- The maximum likelihood estimate  $(\hat{\mu}, \hat{\sigma})$  is the value of  $(\mu, \sigma)$  that maximizes the likelihood function.
- 

## 10.3 Log-likelihood function in the normal case

- We found the log-likelihood function

$$L(\mu, \sigma) = \prod_i \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y_i - \mu)^2}{2\sigma^2}}. \quad (2)$$

- Again it is easier to maximize the log-likelihood function.

$$\begin{aligned} l(\mu, \sigma) &= \ln(L(\mu, \sigma)) = \sum_i \ln\left(\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y_i - \mu)^2}{2\sigma^2}}\right) \\ &= \sum_i \left(-\ln(\sigma\sqrt{2\pi}) - \frac{(y_i - \mu)^2}{2\sigma^2}\right) = -n \ln(\sigma\sqrt{2\pi}) - \sum_i \frac{(y_i - \mu)^2}{2\sigma^2} \end{aligned}$$

- We find the partial derivatives and set them equal to 0. First with respect to  $\mu$ :

$$\frac{\partial}{\partial \mu} l(\mu, \sigma) = \sum_i \frac{2(y_i - \mu)}{2\sigma^2} = \frac{1}{\sigma^2} \sum_i (y_i - \mu) = \frac{1}{\sigma^2} \left(\sum_i y_i - n\mu\right) = 0$$

- Vi får at  $n\mu = \sum_i y_i$ , så  $\mu = \frac{1}{n} \sum_i y_i = \bar{y}$ .

- Then with respect to  $\sigma$ :

$$\frac{\partial}{\partial \sigma} l(\mu, \sigma) = -\frac{n}{\sigma} + \sum_i \frac{(y_i - \mu)^2}{\sigma^3} = 0$$

- We multiply by  $\sigma$  and insert  $\mu = \bar{y}$ :

$$-n + \sum_i \frac{(y_i - \bar{y})^2}{\sigma^2} = 0$$

$$n = \frac{1}{\sigma^2} \sum_i (y_i - \bar{y})^2$$

$$\sigma^2 = \frac{1}{n} \sum_i (y_i - \bar{y})^2$$

- In total we get the maximum likelihood estimates:

$$\hat{\mu} = \frac{1}{n} \sum_i y_i = \bar{y}$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_i (y_i - \bar{y})^2$$


---

## 10.4 Numerical solution - normal distribution

- The maximum likelihood estimates can also be found numerically. We consider again the `trees` data.

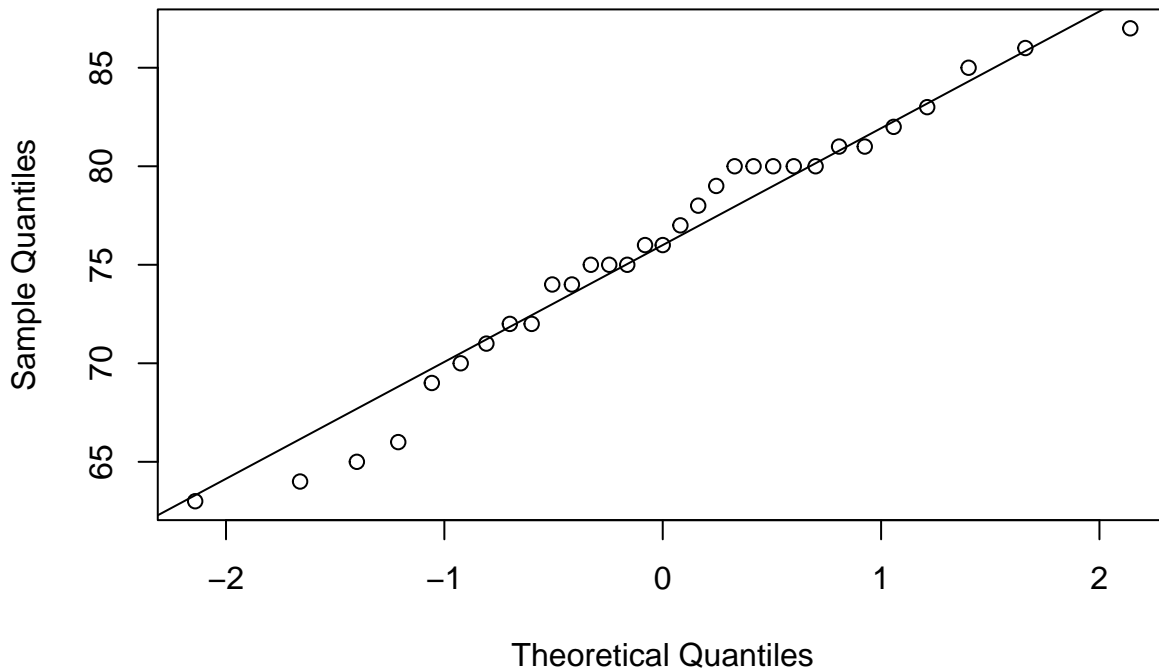
```
trees <- read.delim("https://asta.math.aau.dk/datasets?file=trees.txt")
head(trees)
```

```
##   Girth Height Volume
## 1   8.3     70     10
## 2   8.6     65     10
## 3   8.8     63     10
## 4  10.5     72     16
## 5  10.7     81     19
## 6  10.8     83     20
```

- We will assume that the variable `Height` is normally distributed.

```
qqnorm(trees$Height)
qqline(trees$Height)
```

### Normal Q-Q Plot



## 10.5 Numerical solution - normal distribution

- We define the log-likelihood as a function of the parameter vector  $\theta = (\mu, \sigma)^T$ .

- `dnorm(y, mean = mu, sd = sigma)` gives the normal density  $f(y)$  with mean  $\mu$  and standard deviation  $\sigma$  evaluated at  $y$ .

```
loglik_normal <- function(theta) {
  mu <- theta[1]
  sigma <- theta[2]
  y<-trees$Height
  fy<-dnorm(y , mean = mu, sd = sigma)
  sum(log(fy))
}
loglik_normal(c(1,5))
```

```
## [1] -3590
```

- We maximize again using `optim()`:

```
optim(c(1, 5), loglik_normal, control=list(fnscale=-1))
```

```
## $par
## [1] 76.0 6.3
##
## $value
## [1] -101
##
## $counts
## function gradient
##      103      NA
##
## $convergence
## [1] 0
##
## $message
## NULL
```

- We can compare this to the theoretical formulas for the maximum likelihood estimates:

$$\hat{\mu} = \bar{y},$$

$$\hat{\sigma} = \sqrt{\frac{1}{n} \sum_i (y_i - \bar{y})^2} = \sqrt{\frac{n-1}{n}} s.$$

```
mean(trees$Height)
```

```
## [1] 76
```

```
sd(trees$Height)
```

```
## [1] 6.4
```

```
n <- length(trees$Height)
sd(trees$Height)*sqrt((n-1)/n)
```

```
## [1] 6.3
```

## 11 Properties of maximum likelihood estimators

- Suppose  $\theta \in \mathbb{R}$  is a parameter that we estimate by  $\hat{\theta}$  using maximum likelihood estimation. Then (under suitable conditions) one may show the following mathematically.



- **Consistency:** For all  $\varepsilon > 0$ ,

$$\lim_{n \rightarrow \infty} P(|\theta - \hat{\theta}| > \varepsilon) = 0$$

- **Central limit theorem:** When  $n \rightarrow \infty$ ,

$$\sqrt{n}(\hat{\theta} - \theta) \rightarrow N(0, \sigma_{\hat{\theta}}^2).$$

That is, for large  $n$ ,

$$\sqrt{n}(\hat{\theta} - \theta) \approx N(0, \sigma_{\hat{\theta}}^2),$$

or equivalently,

$$\hat{\theta} \approx N\left(\theta, \frac{\sigma_{\hat{\theta}}^2}{n}\right).$$