Probability 2

The ASTA team

Contents

1	Two	random variables	2
	1.1	Joint distribution of two discrete variables	2
	1.2	Marginal distributions and independence	2
	1.3	Joint distribution of two continuous variables	3
	1.4	Marginal distributions and independence	4
	1.5	Covariance	4
	1.6	Correlation	4
2	The	normal distribution	5
	2.1	Definition of the normal distribution	5
	2.2	The normal distribution - interpretation of parameters	5
	2.3	Normal z-scores	6
	2.4	Probabilities in a normal distribution	6
	2.5	Getting started with R	7
	2.6	Computing probabilities in a normal distribution	8
	2.7	Calculating z -values in the standard normal distribution	9
3	Sam	pling	12
	3.1	Population and sample	12
	3.2	Sampling principles	12
	3.3	Statistical inference	13
	3.4	Sample proportion	13
	3.5	A real experiment	13
	3.6	Sample mean	14
	3.7	Central limit theorem	15
	3.8	Illustration of CLT	15
	3.9	Sample variance and standard deviation	17
	3.10	The χ^2 -distribution	17
	3.11	z-scores for the sample mean	18
	2 12	t distribution and t score	10

1 Two random variables

1.1 Joint distribution of two discrete variables

• Let X and Y be two discrete random variables. The **joint distribution** of X and Y is given by their **joint probability function**

$$f(x,y) = P(X = x, Y = y).$$

• We find the probability of $(X,Y) \in A$ by summing probabilities:

$$P((X,Y) \in A) = \sum_{(x,y)\in A} f(x,y).$$

• **Example:** We roll two dies and let X be the outcome of die 1 and Y be the outcome of die 2. Since all 36 combinations are equally likely,

$$f(x,y) = P(X = x, Y = y) = \frac{1}{36}, \quad x, y = 1, 2, \dots, 6.$$

We can now compute:

$$P(X + Y = 4) = f(1,3) + f(2,2) + f(3,1) = \frac{1}{36} + \frac{1}{36} + \frac{1}{36} = \frac{1}{12}.$$

1.2 Marginal distributions and independence

• Let (X,Y) be a pair of discrete variables with joint probability function f(x,y). The **marginal** probability function for X is found by

$$f(x) = P(X = x) = \sum_{y} P(X = x, Y = y) = \sum_{y} f(x, y).$$

• Similarly, the marginal probability function for Y is

$$g(y) = \sum_{x} f(x, y).$$

• We say that X and Y are **independent** if

$$f(x,y) = f(x)g(y).$$

• Note: Recalling the definition of the probability function, the independence condition says that

$$f(x,y) = P(X = x, Y = y) = P(X = x) \cdot P(Y = y) = f(x)g(y),$$

2

which corresponds to independence of the events $\{X = x\}$ and $\{Y = y\}$.

• **Example:** We roll two dice and let X and Y be the outcome of die 1 and die 2, respectively. We found earlier that $f(x,y) = \frac{1}{36}$ for $x,y=1,2,\ldots,6$. From this we can find the marginal distribution of X

$$f(x) = \sum_{y=1}^{6} f(x,y) = \frac{1}{36} + \frac{1}{36} + \frac{1}{36} + \frac{1}{36} + \frac{1}{36} + \frac{1}{36} = \frac{1}{6}, \quad x = 1, 2, \dots, 6,$$

as we would expect. Similarly, the marginal distribution of Y is $g(y) = \frac{1}{6}$, y = 1, 2, ..., 6. We can now check that the two dice are statistically independent:

$$f(x,y) = \frac{1}{36} = \frac{1}{6} \cdot \frac{1}{6} = f(x)g(y).$$

1.3 Joint distribution of two continuous variables

- Let X and Y be two continuous random variables. The **joint distribution** of X and Y is given by their **joint density function** f(x, y).
- We find the probability of $(X,Y) \in A$ we integrate over A:

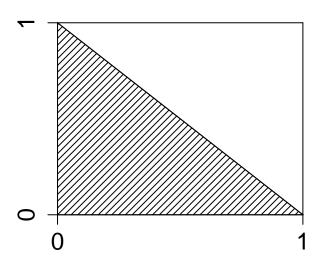
$$P((X,Y) \in A) = \iint_A f(x,y) dx dy.$$

• Example: Suppose that (X,Y) have the joint density

$$f(x,y) = \begin{cases} 1, & 0 \le x, y \le 1 \\ 0, & \text{otherwise.} \end{cases}$$

Suppose we want to find the probability $P(X + Y \le 1)$. This means (X, Y) should belong to the set $A = \{(x, y) : x + y \le 1\}$. Thus,

$$P(X+Y\leq 1) = \iint_A f(x,y) dx dy = \int_0^1 \int_0^{1-x} 1 dy dx = \int_0^1 [y]_0^{1-x} = \int_0^1 (1-x) dx = [-\frac{1}{2}(1-x)^2]_0^1 = \frac{1}{2}.$$



1.4 Marginal distributions and independence

• Let (X, Y) be a pair of continuous variables with joint density function f(x, y). Then the **marginal** density functions for X and Y is found by the formula

$$f(x) = \int_{-\infty}^{\infty} f(x, y) dy, \qquad g(y) = \int_{-\infty}^{\infty} f(x, y) dx.$$

• We say that X and Y are **independent** if

$$f(x,y) = f(x)g(y).$$

1.5 Covariance

• For two random variables, the dependence between them can be measured by the **covariance** between them. This is given by

$$\sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \sum_{(x,y)} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(x - \mu_X)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)f(x,y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y), \sigma_{XY} = E((X - \mu_X)(Y - \mu_Y))$$

in the discrete and continuous case, respectively.

- Properties:
- $\sigma_{XY} > 0$ indicates that the values of X tend to be large when Y is large and X tends to be small when Y is small.
- $\sigma_{XY} < 0$ indicates that the values of X tend to be large when Y is small and small when Y is large.
- If X and Y are statistically independent, then $\sigma_{XY} = 0$.
- If $\sigma_{XY} = 0$ it is not guaranteed that X and Y are independent!
- Apart from this, the values of σ_{XY} are hard to interpret since they depend on the units that X and Y are measured in.

1.6 Correlation

• To obtain a unit free version of the covariance, we define the correlation coefficient

$$\rho_{XY} = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}.$$

This can be thought of as the covariance when X and Y are measured in standard deviation units.

- Properties:
- $-1 \le \rho_{XY} \le 1$.
- $\rho_{XY} = 1$ means one of the variables is linearly determined by the other, say Y = a + bX, where the slope b > 0.

- $\rho_{XY} = -1$ means one of the variables is linearly determined by the other, say Y = a + bX, where the slope b < 0.
- If X and Y are independent, then $\rho_{XY} = 0$. Again, one cannot conclude that X and Y are independent if $\rho_{XY} = 0$.
- More on correlation in Module 3.

2 The normal distribution

2.1 Definition of the normal distribution

• The normal distribution is a continuous distribution with probability density function

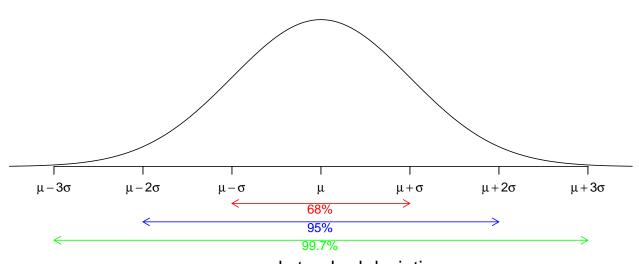
$$n(x; \mu, \sigma) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}.$$

- It depends on two parameters:
- The mean μ
- The standard deviation σ
- When a random variable Y follows a normal distribution with mean μ and standard deviation σ , we write $Y \sim \text{norm}(\mu, \sigma)$.

2.2 The normal distribution - interpretation of parameters

• The probability density function of a normal distribution is a symmetric bell-shaped curve centered around μ .

Density of the normal distribution



mean μ and standard deviation σ

- Interpretation of standard deviation:
- $\approx 68\%$ of the population is within 1 standard deviation of the mean.
- $\approx 95\%$ of the population is within 2 standard deviations of the mean.
- $\approx 99.7\%$ of the population is within 3 standard deviations of the mean.

2.3 Normal z-scores

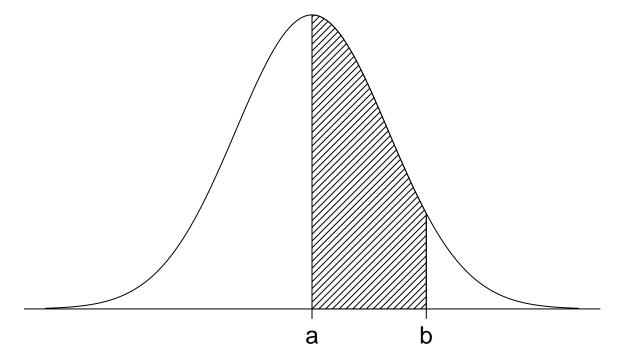
- The normal distribution with mean $\mu = 0$ and standard deviation $\sigma = 1$ is called the **standard normal** distribution.
- If $Y \sim \text{norm}(\mu, \sigma)$ then the corresponding z-score is

$$Z = \frac{Y - \mu}{\sigma}$$

- Interpretation: Z is the number of standard deviations that Y is away from the mean, where a negative value tells that we are below the mean.
- We have that $Z \sim \text{norm}(0,1)$, i.e. Z follows a standard normal distribution.
- This implies that
 - Z lies between -1 and 1 with probability 68%
 - -Z lies between -2 and 2 with probability 95%
 - -Z lies between -3 and 3 with probability 99.7%
- It also implies that:
 - The probability of Y being between $\mu z\sigma$ and $\mu + z\sigma$ is equal to the probability of Z being between -z and z.

2.4 Probabilities in a normal distribution

• To find the probabilities P(a < X < b) in a normal distribution, we need to find the area under the density curve:



• This is given by

$$P(a < X < b) = \int_{a}^{b} \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^{2}}{2\sigma^{2}}} dx.$$

• This integral cannot be computed by hand!

2.5 Getting started with R

- To calculate normal probabilities in R we use the mosaic package.
- The first time you use the mosaic package, you need to install it first. This is done via the command:

install.packages("mosaic")

• At the beginning of each new R session you need to load it through the library command:

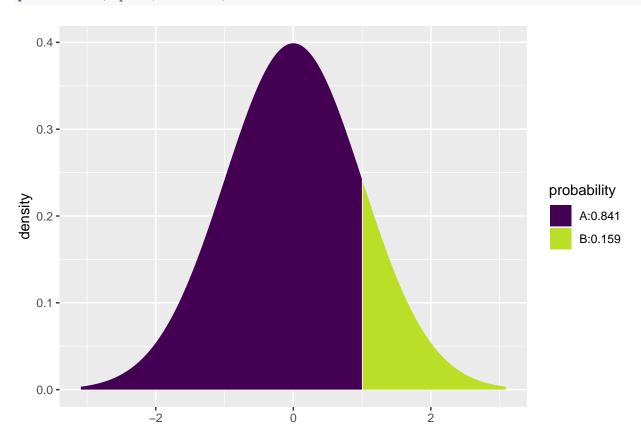
library(mosaic)

• This loads the mosaic package which has a lot of convenient functions for this course (we will get back to that later). It also prints a lot of info about functions that have been changed by the mosaic package, but you can safely ignore that.

2.6 Computing probabilities in a normal distribution

- To find the probability $P(X \leq q)$ when $X \sim \text{norm}(\mu, \sigma)$, we use the pdist function in \mathbf{R} .
- For instance with $q=1, \mu=0$ and $\sigma=1$, we type

For a standard normal distribution the probability of getting a value less than 1 is: pdist("norm", q = 1, mean = 0, sd = 1)



[1] 0.8413447

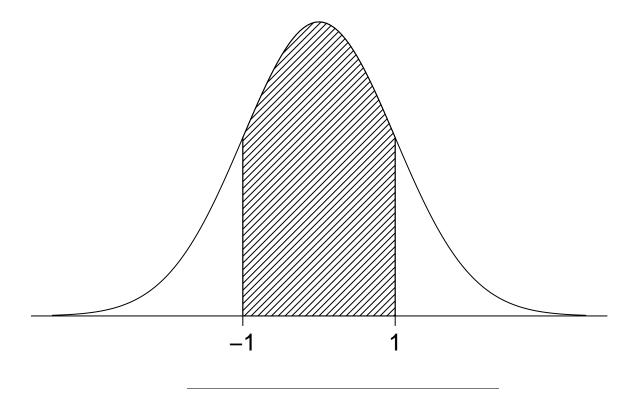
- The output is always the probability of being to the left of q, which is marked as the purple area.
- To get the probability of being to the right of q, we compute

$$P(X > q) = 1 - P(X \le q) = 1 - 0.8413447 = 0.1586553.$$

• We can also get the probability of an observation lying between -1 and 1 by

$$P(-1 \le X \le 1) = 1 - P(X > 1) - P(X < -1) = 1 - 2 \cdot 0.1587 = 0.683,$$

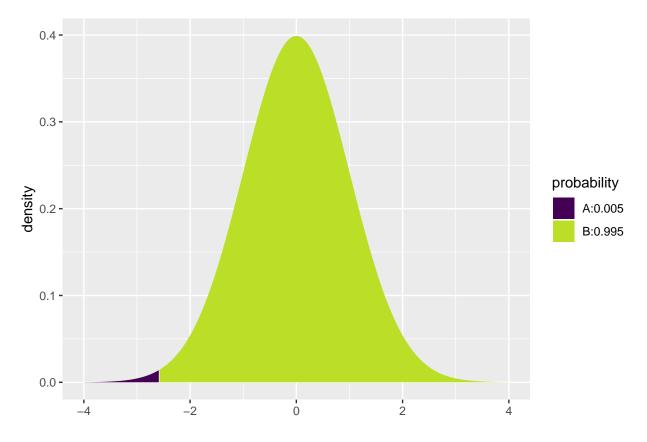
where we used that by symmetry of the normal curve, P(X > 1) = P(X < -1).



2.7 Calculating z-values in the standard normal distribution

- We can also go in the other direction using qdist: Given a probability p, find the value z such that $P(X \le z) = p$ when $X \sim \text{norm}(\mu, \sigma)$.
- For instance with $p=0.005,\,\mu=0$ and $\sigma=1$:

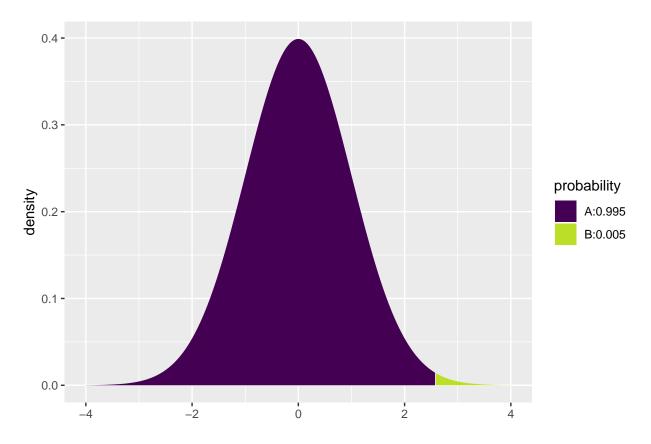
```
qdist("norm", p = 0.005, mean = 0, sd = 1, xlim = c(-4, 4))
```



[1] -2.575829

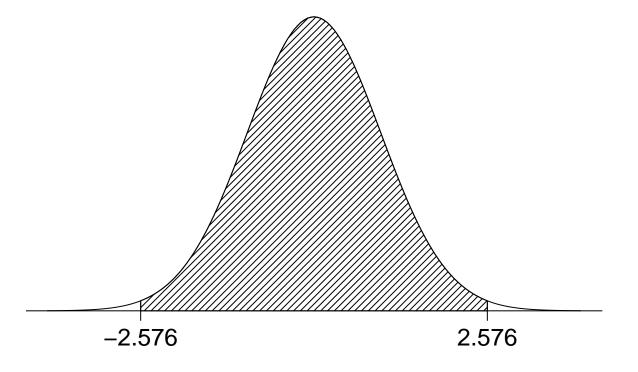
• Sometimes we want to find z such that P(X > z) = p. Since this is the same as $P(X \le z) = 1 - p$, we may do as follows:

```
qdist("norm", p = 1-0.005, mean = 0, sd = 1, xlim = c(-4, 4))
```



[1] 2.575829

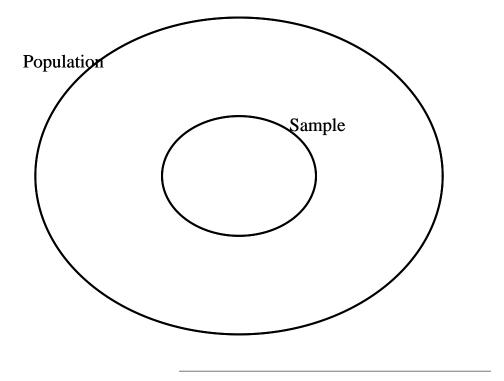
• Thus, the probability of an observation between -2.576 and 2.576 equals $1-2\cdot 0.005=99\%$.



3 Sampling

3.1 Population and sample

- In statistics, the word **population** refers to the collection of all the objects we are interested in.
- Examples:
- The Danish population
- All possible outcomes of a lab experiment
- A **sample** consists of finitely many elements selected randomly and independently of each other from the population.
- Examples:
- People selected for an opinion poll
- The experiments we actually carried out



3.2 Sampling principles

- If we draw a random element from the population, the result will be a random variable X with a certain distribution.
- When we sample, we draw n elements from the population *independently* of each other. This results in n independent random variables X_1, \ldots, X_n , each having the *same distribution* as X.
- Sampling principles:

- Independence: If you make experiments in the lab, reusing parts of an experiment for the next one might cause dependence between outcomes.
- Same distribution as the population: If we only go out and make weather measurements when the
 weather is good, our sample does not have the same distribution as measurements from any randomly
 selected day.
- Note: We use capital letters X_1, \ldots, X_n to indicate that the elements of the sample are random and small letters x_1, \ldots, x_n to denote the values that are actually observed in the experiment. These values are called **observations**.

3.3 Statistical inference

- Statistical inference means drawing conclusions about the population based on the sample.
- Typically, we want to draw conclusions about some parameters of the population, e.g. mean μ and standard deviation σ .
- Note: The number of elements n in the sample is called the **sample size**. In general: the larger n, the more precise conclusions we can draw about the population.

3.4 Sample proportion

- Consider an experiment with two possible outcomes, e.g. flipping a coin or testing whether a component is defect or not.
- Call the two outcomes 0 and 1. We are interested in the probability p of getting the outcome 1.
- Given a sample X_1, \ldots, X_n , we estimate p by

$$\hat{P} = \frac{\text{number of 1's among } X_1, \dots, X_n}{n} = \frac{\sum_{i=1}^n X_i}{n}.$$

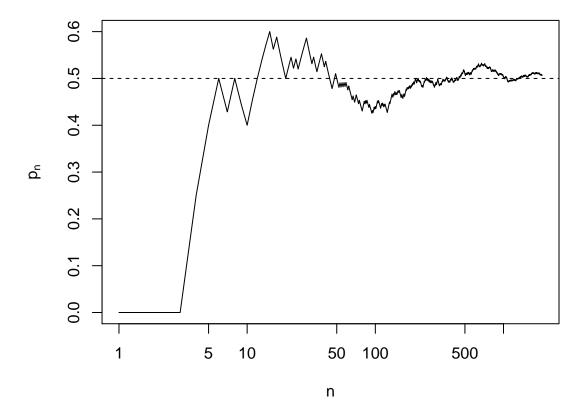
- \hat{P} is a so-called **summary statistics**, i.e. a function of the sample.
- Since \hat{P} is a function of the random sample X_1, \ldots, X_n , \hat{P} is itself a random variable. Different samples may lead to different values of \hat{P} .
- $E(\hat{P}) = p$.
- $\lim_{n\to\infty} \hat{P} = p$.

3.5 A real experiment

- John Kerrich, a South African mathematician, was visiting Copenhagen when World War II broke out. Two days before he was scheduled to fly to England, the Germans invaded Denmark. Kerrich spent the rest of the war interned at a camp in Hald Ege near Viborg, Jutland. To pass the time he carried out a series of experiments in probability theory. In one, he tossed a coin 10,000 times.
- The first 25 observations were (0 = tail, 1 = head):

$$0, 0, 0, 1, 1, 1, 0, 1, 0, 0, 1, 1, 1, 1, 1, 1, 0, 1, 0, 0, 0, 1, 1, 0, 1, 0, \dots$$

• Plot of the empirical probability \hat{p} of getting a head against the number of tosses n:



(The horizontal axis is on a log scale).

3.6 Sample mean

- Suppose we are interested in the mean value μ of a population and we have drawn a random sample X_1, \ldots, X_n .
- Based on the sample we estimate μ by the sample mean, which is the average of all the elements

$$\bar{X} = \frac{1}{n} \sum_{i=1}^{n} X_i.$$

- Properties:
- \bar{X} is random, as it depends on the random sample X_1, \ldots, X_n . Different samples might result in different values of \bar{X} .
- $E(\bar{X}) = \mu$.
- \bar{X} has standard deviation $\frac{\sigma}{\sqrt{n}}$, where σ is the population standard deviation. Note that increasing n decreases $\frac{\sigma}{\sqrt{n}}$.
- To distinguish between the standard deviation of the population and the standard deviation of \bar{X} , we call the standard deviation of \bar{X} the **Standard error**.
- $\lim_{n\to\infty} \bar{X} = \mu$.

3.7 Central limit theorem

• When the population distribution is anormal distribution $norm(\mu, \sigma)$, then

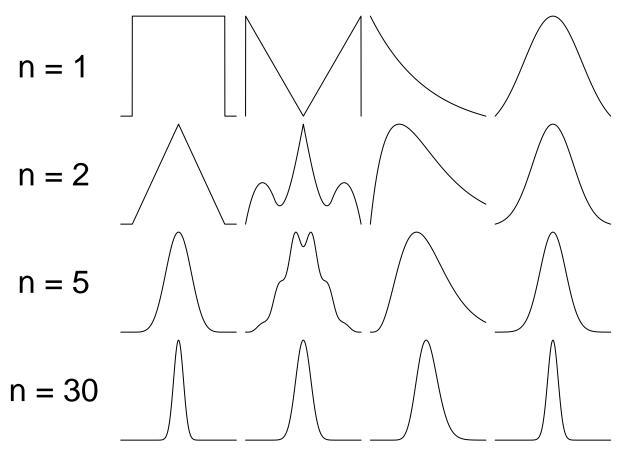
$$\bar{X} \sim \mathtt{norm}\left(\mu, \frac{\sigma}{\sqrt{n}}\right).$$

- For any population distribution, the **central limit theorem** states:
- When n goes to ∞ , the distribution of \bar{X} approaches a normal distribution with mean μ and standard deviation $\frac{\sigma}{\sqrt{n}}$. Thus, for large n,

$$\bar{X} \approx \mathrm{norm}\left(\mu, \frac{\sigma}{\sqrt{n}}\right).$$

• As a rule of thumb, n is large enough when $n \geq 30$.

3.8 Illustration of CLT



• The top row shows 4 different population distributions. The plots below show the distribution of \bar{X} when $n=2,\,5,\,$ and 30.

3.8.1 Example: use of CLT

- A company produces cylindrical components for automobiles. It is important that the mean component diameter is $\mu = 5 \text{mm}$. The standard deviation is $\sigma = 0.1 \text{mm}$.
- An engineer takes a random sample of n=100 components. These have an average diameter of $\bar{x}=5.027$. Is it reasonable to think $\mu=5$?
- If the population of components has the correct mean, then

$$\bar{X} \approx \mathrm{norm}\left(\mu, \frac{\sigma}{\sqrt{n}}\right) = \mathrm{norm}\left(5, \frac{0.1}{\sqrt{100}}\right) = \mathrm{norm}(5, 0.01).$$

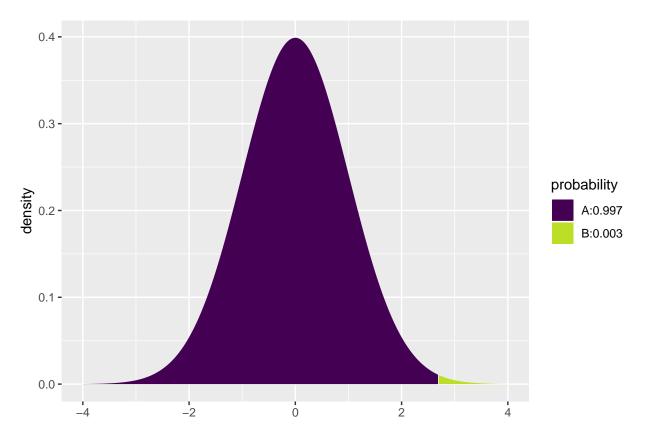
• For the actual sample this gives the observed z-score

$$z_{obs} = \frac{\bar{x} - 5}{0.01} = 2.7$$

which should come from an approximate standard normal distribution.

• The probability of getting a higher z-score is:

1 - pdist("norm", mean = 0, sd = 1, q = 2.7, xlim = c(-4, 4))



[1] 0.003466974

• Thus, it is highly unlikely that a random sample has such a high z-score. A better explanation might be that the produced components have a population mean larger than 5mm.

3.9 Sample variance and standard deviation

- Suppose we are interested in the variance σ^2 of a population and we have drawn a random sample X_1, \ldots, X_n .
- Based on the sample we estimate the population variance σ^2 by the sample variance, which is

$$S^{2} = \frac{1}{n-1} \sum_{i=1}^{n} (X_{i} - \bar{X})^{2}.$$

• We estimate the population standard deviation σ by the sample standard deviation

$$S = \sqrt{S^2}$$

- Properties:
- S^2 is again a random variable.
- $E(S^2) = \sigma^2$.
- When the population distribution is normal, or $n \geq 30$,

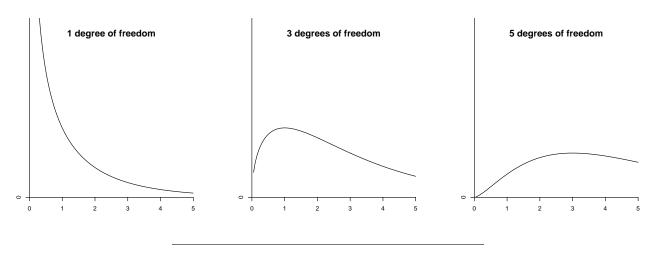
$$\frac{(n-1)S^2}{\sigma^2} \sim \chi^2(n-1),$$

where $\chi^2(n-1)$ is the **chi-square distribution** with (n-1) degrees of freedom (se next slide).

• As a rule of thumb, the degrees of freedom are found as the number of observations (n) minus the number of unknown parameters describing the mean (one, namely μ).

3.10 The χ^2 -distribution

- The distribution $\chi^2(k)$ is called the **chi-square** distribution.
- It is a distribution on $(0, \infty)$.
- It depends on a the parameter k called the **degrees of freedom**.
- The degrees of freedom determine the shape of the distribution.
- The mean value is k.



3.11 z-scores for the sample mean

- According to the central limit theorem $\bar{X} \approx \text{norm}(\mu, \frac{\sigma}{\sqrt{n}})$ when the population follows a normal distribution or n is large.
- The corresponding z-score $Z = \frac{\bar{X} \mu}{\sigma/\sqrt{n}}$ follows a standard normal distribution norm(0,1).
- Problem: We don't know σ .
- We may insert the sample standard deviation to get the t-score

$$T = \frac{\bar{X} - \mu}{S/\sqrt{n}}.$$

- Since S is random with a certain variance, this causes T to vary more than Z.
- As a consequence, T no longer follows a normal distribution, but a t-distribution with n-1 degrees of freedom.

3.12 *t*-distribution and *t*-score

- The *t*-distribution is very similar to the standard normal distribution:
 - it is symmetric around zero and bell shaped, but
 - it has "heavier" tails and thereby
 - a slightly larger standard deviation than the standard normal distribution.
 - Further, the t-distribution's standard deviation decays as a function of its **degrees of freedom**, which we denote df,
 - and when df grows, the t-distribution approaches the standard normal distribution.

The expression of the density function is of slightly complicated form and will not be stated here, instead the t-distribution is plotted below for df = 1, 2, 10 and ∞ .

